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> # Prof. Dr. Serkan Dağ
> # ME 451 Introduction to Composite Structures
> # File 7.1
> # Example on failure loads of a laminate

> restart :
with(LinearAlgebra) :
> # Enter the number of plies
> n := 3 :
> # Define extensional, coupling, and bending stiffness matrices
> A := Matrix(3) :
  B := Matrix(3) :
  Dm := Matrix(3) :
> # Define ply surface coordinate vector in meters
> h :=  $\begin{bmatrix} -\frac{7.5}{1000} \\ -\frac{2.5}{1000} \\ \frac{2.5}{1000} \\ \frac{7.5}{1000} \end{bmatrix}$  :
> # Define ply angle vector in radians
> theta :=  $\begin{bmatrix} 0 \\ \frac{\text{Pi}}{2} \\ 0 \end{bmatrix}$  :
> # Define Qbar array
Qbar := Array(1..3, 1..3, 1..n) :
ArrayNumElems(Qbar);

27

> # Enter properties of the unidirectional lamina
> # From Table 2.1 for graphite/epoxy (unit = MPa)
> E1 := 181000 :
  E2 := 10300 :
  nu12 := 0.28 :
  G12 := 7170 :
> # Calculate elements of the compliance matrix for the
  unidirectional lamina
> S11 :=  $\frac{1}{E1}$  :
  S12 :=  $-\frac{\text{nu12}}{E1}$  :
  S22 :=  $\frac{1}{E2}$  :

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$$S66 := \frac{1}{G12} :$$

> # Calculate elements of the reduced stiffness matrix for the unidirectional lamina

$$Q11 := \frac{S22}{S11 \cdot S22 - S12^2} :$$

$$Q22 := \frac{S11}{S11 \cdot S22 - S12^2} :$$

$$Q12 := -\frac{S12}{S11 \cdot S22 - S12^2} :$$

$$Q66 := \frac{1}{S66} :$$

> # Calculate elements of transformed reduced stiffness matrix for each angle lamina

# Unit = MPa

> for i from 1 by 1 to n  
while true do

$$Qbar[1, 1, i] := Q11 \cdot (\cos(\text{theta}[i, 1]))^4 + Q22 \cdot (\sin(\text{theta}[i, 1]))^4 + 2 \cdot (Q12 + 2 \cdot Q66) \cdot (\cos(\text{theta}[i, 1]))^2 \cdot (\sin(\text{theta}[i, 1]))^2 :$$

$$Qbar[1, 2, i] := (Q11 + Q22 - 4 \cdot Q66) \cdot (\sin(\text{theta}[i, 1]))^2 \cdot (\cos(\text{theta}[i, 1]))^2 + Q12 \cdot ((\cos(\text{theta}[i, 1]))^4 + (\sin(\text{theta}[i, 1]))^4) :$$

$$Qbar[1, 3, i] := (Q11 - Q12 - 2 \cdot Q66) \cdot (\sin(\text{theta}[i, 1])) \cdot (\cos(\text{theta}[i, 1]))^3 - (Q22 - Q12 - 2 \cdot Q66) \cdot (\sin(\text{theta}[i, 1]))^3 \cdot \cos(\text{theta}[i, 1]) :$$

$$Qbar[2, 2, i] := Q11 \cdot (\sin(\text{theta}[i, 1]))^4 + Q22 \cdot (\cos(\text{theta}[i, 1]))^4 + 2 \cdot (Q12 + 2 \cdot Q66) \cdot (\cos(\text{theta}[i, 1]))^2 \cdot (\sin(\text{theta}[i, 1]))^2 :$$

$$Qbar[2, 3, i] := (Q11 - Q12 - 2 \cdot Q66) \cdot (\cos(\text{theta}[i, 1])) \cdot (\sin(\text{theta}[i, 1]))^3 - (Q22 - Q12 - 2 \cdot Q66) \cdot (\cos(\text{theta}[i, 1]))^3 \cdot \sin(\text{theta}[i, 1]) :$$

$$Qbar[3, 3, i] := (Q11 + Q22 - 2 \cdot Q12 - 2 \cdot Q66) \cdot (\cos(\text{theta}[i, 1]))^2 \cdot (\sin(\text{theta}[i, 1]))^2 + Q66 \cdot ((\cos(\text{theta}[i, 1]))^4 + (\sin(\text{theta}[i, 1]))^4) :$$

$$Qbar[2, 1, i] := Qbar[1, 2, i] :$$

$$Qbar[3, 1, i] := Qbar[1, 3, i] :$$

$$Qbar[3, 2, i] := Qbar[2, 3, i] :$$

end do

> # Calculate elements of extensional stiffness matrix [A], coupling stiffness matrix [B], and bending stiffness matrix [Dm]  
# Units: [A]--> MPa.m; [B]--> MPa.m^2; [Dm]--> MPa.m^3

> for i from 1 by 1 to 3  
while true do

for j from 1 by 1 to 3

while true do

$$A[i, j] = 0 :$$

$$B[i, j] := 0 :$$

$$Dm[i, j] := 0 :$$

for k from 1 by 1 to n

while true do

$$A[i, j] := A[i, j] + Qbar[i, j, k] \cdot (h[k + 1, 1] - h[k, 1]) :$$

$$B[i, j] := B[i, j] + \frac{1}{2} \cdot Qbar[i, j, k] \cdot (h[k + 1, 1]^2 - h[k, 1]^2) :$$

$$Dm[i, j] := Dm[i, j] + \frac{1}{3} \cdot Qbar[i, j, k] \cdot (h[k + 1, 1]^3 - h[k, 1]^3) :$$

**end do:**

**end do:**

**end do:**

> evalf( A );

$$\begin{bmatrix} 1869.842182 & 43.45386666 & 0. \\ 43.45386666 & 1012.517281 & 0. \\ 0. & 0. & 107.5500000 \end{bmatrix}$$

(2)

> evalf( B );

$$\begin{bmatrix} 0. & 0. & 0. \\ 0. & 0. & 0. \\ 0. & 0. & 0. \end{bmatrix}$$

(3)

> evalf( Dm );

$$\begin{bmatrix} 0.04934828925 & 0.0008147599997 & 0. \\ 0.0008147599997 & 0.004695950685 & 0. \\ 0. & 0. & 0.002016562500 \end{bmatrix}$$

(4)

> Astar := MatrixInverse( A );

$$Astar := \begin{bmatrix} 5.353 \times 10^{-4} & -2.297 \times 10^{-5} & 0.000 \times 10^0 \\ -2.297 \times 10^{-5} & 9.886 \times 10^{-4} & 0.000 \times 10^0 \\ 0.000 \times 10^0 & 0.000 \times 10^0 & 9.298 \times 10^{-3} \end{bmatrix}$$

(5)

> # Define load vector

$$N := \begin{bmatrix} Nx \\ 0 \\ 0 \end{bmatrix};$$

$$N := \begin{bmatrix} Nx \\ 0 \\ 0 \end{bmatrix}$$

(6)

> # Find strains (Note that strains in this case are equal to mid-plane strains)

> Eps := Multiply( Astar, N );

$$Eps := \begin{bmatrix} 5.3534 \times 10^{-4} Nx \\ -2.2975 \times 10^{-5} Nx \\ 0.0000 \times 10^0 \end{bmatrix}$$

(7)

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> # Calculate global stresses in the 0-degree ply (n=1)
>  $\sigma_{max1} := Q_{bar}[1, 1, 1] \cdot Eps[1, 1] + Q_{bar}[1, 2, 1] \cdot Eps[2, 1] + Q_{bar}[1, 3, 1] \cdot Eps[3, 1];$ 
 $\sigma_{may1} := Q_{bar}[2, 1, 1] \cdot Eps[1, 1] + Q_{bar}[2, 2, 1] \cdot Eps[2, 1] + Q_{bar}[2, 3, 1] \cdot Eps[3, 1];$ 
 $\tau_{axy1} := Q_{bar}[3, 1, 1] \cdot Eps[1, 1] + Q_{bar}[3, 2, 1] \cdot Eps[2, 1] + Q_{bar}[3, 3, 1] \cdot Eps[3, 1];$ 
 $\sigma_{max1} := 97.26393020 \text{ Nx}$ 
 $\sigma_{may1} := 1.313132561 \text{ Nx}$ 
 $\tau_{axy1} := 0.$ 

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(8)

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> # Calculate global stresses in the 90-degree ply (n=2)
>  $\sigma_{max2} := Q_{bar}[1, 1, 2] \cdot Eps[1, 1] + Q_{bar}[1, 2, 2] \cdot Eps[2, 1] + Q_{bar}[1, 3, 2] \cdot Eps[3, 1];$ 
 $\sigma_{may2} := Q_{bar}[2, 1, 2] \cdot Eps[1, 1] + Q_{bar}[2, 2, 2] \cdot Eps[2, 1] + Q_{bar}[2, 3, 2] \cdot Eps[3, 1];$ 
 $\tau_{axy2} := Q_{bar}[3, 1, 2] \cdot Eps[1, 1] + Q_{bar}[3, 2, 2] \cdot Eps[2, 1] + Q_{bar}[3, 3, 2] \cdot Eps[3, 1];$ 
 $\sigma_{max2} := 5.472139550 \text{ Nx}$ 
 $\sigma_{may2} := -2.626265123 \text{ Nx}$ 
 $\tau_{axy2} := 0.$ 

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(9)

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> # Calculate global stresses in the 90-degree ply (n=3)
>  $\sigma_{max3} := Q_{bar}[1, 1, 3] \cdot Eps[1, 1] + Q_{bar}[1, 2, 3] \cdot Eps[2, 1] + Q_{bar}[1, 3, 3] \cdot Eps[3, 1];$ 
 $\sigma_{may3} := Q_{bar}[2, 1, 3] \cdot Eps[1, 1] + Q_{bar}[2, 2, 3] \cdot Eps[2, 1] + Q_{bar}[2, 3, 3] \cdot Eps[3, 1];$ 
 $\tau_{axy3} := Q_{bar}[3, 1, 3] \cdot Eps[1, 1] + Q_{bar}[3, 2, 3] \cdot Eps[2, 1] + Q_{bar}[3, 3, 3] \cdot Eps[3, 1];$ 
 $\sigma_{max3} := 97.26393020 \text{ Nx}$ 
 $\sigma_{may3} := 1.313132561 \text{ Nx}$ 
 $\tau_{axy3} := 0.$ 

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(10)

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> # Calculate local stresses in the 0-degree ply (n=1)
>  $\sigma_{l11} := (\cos(\theta[1, 1]))^2 \cdot \sigma_{max1} + (\sin(\theta[1, 1]))^2 \cdot \sigma_{may1} + 2 \cdot \sin(\theta[1, 1])$ 
 $\cdot \cos(\theta[1, 1]) \cdot \tau_{axy1};$ 
 $\sigma_{l21} := (\sin(\theta[1, 1]))^2 \cdot \sigma_{max1} + (\cos(\theta[1, 1]))^2 \cdot \sigma_{may1} - 2 \cdot \sin(\theta[1, 1])$ 
 $\cdot \cos(\theta[1, 1]) \cdot \tau_{axy1};$ 
 $\tau_{l21} := -\sin(\theta[1, 1]) \cdot \cos(\theta[1, 1]) \cdot \sigma_{max1} + \sin(\theta[1, 1]) \cdot \cos(\theta[1, 1])$ 
 $\cdot \sigma_{may1} + ((\cos(\theta[1, 1]))^2 - (\sin(\theta[1, 1]))^2) \cdot \cos(\theta[1, 1]) \cdot \tau_{axy1};$ 
 $\sigma_{l11} := 97.26393020 \text{ Nx}$ 
 $\sigma_{l21} := 1.313132561 \text{ Nx}$ 
 $\tau_{l21} := 0.$ 

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(11)

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> # Calculate local stresses in the 90-degree ply (n=2)
>  $\sigma_{l12} := (\cos(\theta[2, 1]))^2 \cdot \sigma_{max2} + (\sin(\theta[2, 1]))^2 \cdot \sigma_{may2} + 2 \cdot \sin(\theta[2, 1])$ 
 $\cdot \cos(\theta[2, 1]) \cdot \tau_{axy2};$ 
 $\sigma_{l22} := (\sin(\theta[2, 1]))^2 \cdot \sigma_{max2} + (\cos(\theta[2, 1]))^2 \cdot \sigma_{may2} - 2 \cdot \sin(\theta[2, 1])$ 
 $\cdot \cos(\theta[2, 1]) \cdot \tau_{axy2};$ 
 $\tau_{l22} := -\sin(\theta[2, 1]) \cdot \cos(\theta[2, 1]) \cdot \sigma_{max2} + \sin(\theta[2, 1]) \cdot \cos(\theta[2, 1])$ 
 $\cdot \sigma_{may2} + ((\cos(\theta[2, 1]))^2 - (\sin(\theta[2, 1]))^2) \cdot \cos(\theta[2, 1]) \cdot \tau_{axy2};$ 
 $\sigma_{l12} := -2.626265123 \text{ Nx}$ 
 $\sigma_{l22} := 5.472139550 \text{ Nx}$ 
 $\tau_{l22} := 0.$ 

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(12)

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> # Calculate local stresses in the 0-degree ply (n=3)
>  $\sigma_{l13} := (\cos(\theta[3, 1]))^2 \cdot \sigma_{max3} + (\sin(\theta[3, 1]))^2 \cdot \sigma_{may3} + 2 \cdot \sin(\theta[3, 1])$ 
 $\cdot \cos(\theta[3, 1]) \cdot \tau_{axy3};$ 

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$$\begin{aligned} \sigma_{23} &:= (\sin(\theta_{3,1}))^2 \cdot \sigma_{max3} + (\cos(\theta_{3,1}))^2 \cdot \sigma_{may3} - 2 \cdot \sin(\theta_{3,1}) \\ &\quad \cdot \cos(\theta_{3,1}) \cdot \tau_{axy3}; \\ \tau_{123} &:= -\sin(\theta_{3,1}) \cdot \cos(\theta_{3,1}) \cdot \sigma_{max3} + \sin(\theta_{3,1}) \cdot \cos(\theta_{3,1}) \\ &\quad \cdot \sigma_{may3} + ((\cos(\theta_{3,1}))^2 - (\sin(\theta_{3,1}))^2) \cdot \cos(\theta_{3,1}) \cdot \tau_{axy3}; \\ \sigma_{13} &:= 97.26393020 \text{ Nx} \\ \sigma_{23} &:= 1.313132561 \text{ Nx} \\ \tau_{123} &:= 0. \end{aligned} \tag{13}$$

> # Input strength values for graphite/epoxy lamina

>  $\sigma_{1Tult} := 1500$  :  
 $\sigma_{1Cult} := 1500$  :  
 $\sigma_{2Tult} := 40$  :  
 $\sigma_{2Cult} := 246$  :  
 $\tau_{12ult} := 68$  :

> # Determine coefficients of Tsai-Wu failure criterion

>  $H1 := \frac{1}{\sigma_{1Tult}} - \frac{1}{\sigma_{1Cult}}$  :

$H2 := \frac{1}{\sigma_{2Tult}} - \frac{1}{\sigma_{2Cult}}$  :

$H11 := \frac{1}{\sigma_{1Tult} \cdot \sigma_{1Cult}}$  :

$H22 := \frac{1}{\sigma_{2Tult} \cdot \sigma_{2Cult}}$  :

$H12 := -\frac{1}{2} \cdot \text{sqrt}\left(\frac{1}{\sigma_{1Tult} \cdot \sigma_{1Cult} \cdot \sigma_{2Tult} \cdot \sigma_{2Cult}}\right)$  :

> # Apply Tsai-Wu failure criterion for the 0-degree ply (n=1)

>  $eq1 := H1 \cdot \sigma_{11} + H2 \cdot \sigma_{21} + H11 \cdot \sigma_{11}^2 + H22 \cdot \sigma_{21}^2 + H66 \cdot \tau_{121}^2 + 2 \cdot H12 \cdot \sigma_{11} \cdot \sigma_{21}$ ;

$\text{solve}(eq1 = 1, Nx)$ ;

$eq1 := 0.02749037679 \text{ Nx} + 0.004379800866 \text{ Nx}^2 - 0.00003461258368 \sqrt{615} \text{ Nx}^2$   
 $13.39441731, -21.20099715$

(14)

> # Apply Tsai-Wu failure criterion for the 90-degree ply (n=2)

>  $eq2 := H1 \cdot \sigma_{12} + H2 \cdot \sigma_{22} + H11 \cdot \sigma_{12}^2 + H22 \cdot \sigma_{22}^2 + H66 \cdot \tau_{122}^2 + 2 \cdot H12 \cdot \sigma_{12} \cdot \sigma_{22}$ ;

$\text{solve}(eq2 = 1, Nx)$ ;

$eq2 := 0.1145590190 \text{ Nx} + 0.003046186515 \text{ Nx}^2 + 0.000003894658332 \sqrt{615} \text{ Nx}^2$   
 $7.276559802, -43.72815701$

(15)

> # Calculate mid-plane strain at this level of loading

>  $Nx := 7.276559802$  :

$\epsilon_{sx0} := Eps[1, 1]$ ;

$\epsilon_{sx0} := 0.003895421991$

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