# ME 310 Numerical Methods

## Interpolation

These presentations are prepared by Dr. Cuneyt Sert Mechanical Engineering Department Middle East Technical University Ankara, Turkey csert@metu.edu.tr

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### **Interpolation**

• Estimating intermediate values between precise data points.

• We first fit a function that exactly passes through the given data points and than evaluate intermediate values using this function.



- **Polynomial Interpolation:** A unique n<sup>th</sup> order polynomial passes through n points.
  - Newton's Divided Difference Interpolating Polynomials
  - Lagrange Interpolating Polynomials

• **Spline Interpolation:** Pass different curves (mostly 3<sup>rd</sup> order) through different subsets of the data points.

### **Polynomial Interpolation**

• Given the following n+1 data points

$$(x_1, y_1), (x_2, y_2), (x_3, y_3), \dots, (x_{n+1}, y_{n+1})$$

there is a unique n<sup>th</sup> order polynomial that passes through them

$$p(x) = a_0 + a_1 x + a_2 x^2 + \dots + a_n x^n$$

• The question is to find the coefficients  $a_0$ ,  $a_1$ , . . .,  $a_n$ 

### • Linear Interpolation:



- Given:  $(x_0, y_0)$  and  $(x_1, y_1)$
- A straight line passes from these two points.
- Using similar triangles

$$\frac{f(x) - f(x_0)}{x - x_0} = \frac{f(x_1) - f(x_0)}{x_1 - x_0}$$

$$f(x) = f(x_0) + \frac{f(x_1) - f(x_0)}{x_1 - x_0} (x - x_0)$$
  
or  
$$f_1(x) = b_0 + b_1(x - x_0)$$

Linear interpolation formula

### Polynomial Interpolation

• Quadratic Interpolation:



- $\bullet$  Given: (x\_0, y\_0) , (x\_1, y\_1) and (x\_2, y\_2)
- A parabola passes from these three points.
- Similar to the linear case, the equation of this parabola can be written as

$$f_2(x) = b_0 + b_1(x - x_0) + b_2(x - x_0)(x - x_1)$$

Quadratic interpolation formula

- How to find b<sub>0</sub>, b<sub>1</sub> and b<sub>2</sub> in terms of given quantities?
  - at  $x=x_0$   $f_2(x) = f(x_0) = b_0$   $\rightarrow$   $b_0 = f(x_0)$
  - at  $x=x_1$   $f_2(x) = f(x_1) = b_0 + b_1 x_1$   $\rightarrow$   $b_1 = \frac{f(x_1) f(x_0)}{x_1 x_0}$

• at 
$$x=x_2$$
  $f_2(x) = f(x_2) = b_0 + b_1(x_2-x_0) + b_2(x_2-x_0)(x_2-x_1)$   
 $\rightarrow b_2 = \frac{f(x_2) - f(x_1)}{x_2 - x_1} - \frac{f(x_1) - f(x_0)}{x_1 - x_0}$ 

### Newton's Divided Difference Interpolating Polynomials

• We can generalize the linear and quadratic interpolation formulas for an  $n^{th}$  order polynomial passing through n+1 points

$$f_n(x) = b_0 + b_1(x - x_0) + b_2(x - x_0)(x - x_1) + \dots + b_n(x - x_0)(x - x_1) \dots (x - x_{n-1})$$

where the constants are

$$b_{0} = f(x_{0}) \qquad b_{1} = f[x_{1}, x_{0}] \qquad b_{2} = f[x_{2}, x_{1}, x_{0}] \qquad \dots \qquad b_{n} = f[x_{n'}, x_{n-1'}, \dots, x_{1'}, x_{0}]$$

where the bracketed functions are finite divided differences evaluated recursively

$$\begin{aligned} f[\mathbf{x}_{i}, \mathbf{x}_{j}] &= \frac{f(\mathbf{x}_{i}) - f(\mathbf{x}_{j})}{\mathbf{x}_{i} - \mathbf{x}_{j}} & 1^{\text{st}} \text{ finite divided difference} \\ f[\mathbf{x}_{i}, \mathbf{x}_{j}, \mathbf{x}_{k}] &= \frac{f[\mathbf{x}_{i}, \mathbf{x}_{j}] - f[\mathbf{x}_{j}, \mathbf{x}_{k}]}{\mathbf{x}_{i} - \mathbf{x}_{k}} & 2^{\text{nd}} \text{ finite divided difference} \\ f[\mathbf{x}_{n}, \mathbf{x}_{n-1}, ..., \mathbf{x}_{1}, \mathbf{x}_{0}] &= \frac{f[\mathbf{x}_{n}, \mathbf{x}_{n-1}, ..., \mathbf{x}_{1}] - f[\mathbf{x}_{n-1}, ..., \mathbf{x}_{1}, \mathbf{x}_{0}]}{\mathbf{x}_{n} - \mathbf{x}_{0}} & n^{\text{th}} \text{ finite divided difference} \end{aligned}$$

• There nth order Newton's Divided Difference Interpolating polynomial is

$$f_{n}(x) = f(x_{0}) + (x - x_{0}) f[x_{1}, x_{0}] + (x - x_{0})(x - x_{1}) f[x_{2}, x_{1}, x_{0}] + \dots$$
  
+  $(x - x_{0})(x - x_{1}) \cdots (x - x_{n-1}) f[x_{n}, x_{n-1}, \dots, x_{1}, x_{0}]$ 

#### Example 29:

The following logarithmic table is given.

| х   | f(x) = log(x) |
|-----|---------------|
| 4.0 | 0.60206       |
| 4.5 | 0.6532125     |
| 5.5 | 0.7403627     |
| 6.0 | 0.7781513     |

(a) Interpolate log(5) using the points x=4 and x=6

(b) Interpolate log(5) using the points x=4.5 and x=5.5

Note that the exact value is log(5) = 0.69897

(a) Linear interpolation.  $f(x) = f(x_0) + (x - x_0) f[x_1, x_0]$   $x_0 = 4, x_1 = 6 \rightarrow f[x_1, x_0] = [f(6) - f(4)] / (6 - 4) = 0.0880046$  $f(5) \approx f(4) + (5 - 4) 0.0880046 = 0.690106 \qquad \epsilon_t = 1.27 \%$ 

(b) Again linear interpolation. But this time

 $x_0 = 4.5, x_1 = 5.5 → f[x_1, x_0] = [f(5.5) - f(4.5)] / (5.5 - 4.5) = 0.0871502$  $f(5) ≈ f(4.5) + (5 - 4.5) 0.0871502 = 0.696788 ε_t = 0.3 %$ 

### Example 29 (cont'd):

| х   | f(x) = log(x) |
|-----|---------------|
| 4.0 | 0.6020600     |
| 4.5 | 0.6532125     |
| 5.5 | 0.7403627     |
| 6.0 | 0.7781513     |

(c) Interpolate log(5) using the points x=4.5, x=5.5 and x=6

(c) Quadratic interpolation.

$$\begin{aligned} x_{0} &= 4.5, \, x_{1} = 5.5 \,, \, x_{2} = 6 \rightarrow f[x_{1}, \, x_{0}] = 0.0871502 \quad (\text{already calculated}) \\ f[x_{2}, \, x_{1}] &= [f(6) - f(5.5)] \, / \, (6 - 5.5) = 0.0755772 \\ f[x_{2}, \, x_{1}, \, x_{0}] &= \{f[x_{2}, \, x_{1}] - f[x_{1}, \, x_{0}]\} \, / \, (6 - 4.5) = -0.0077153 \\ f(5) &\approx 0.696788 + (5 - 4.5)(5 - 5.5) \, (-0.0077153) = 0.698717 \qquad \epsilon_{t} = 0.04 \, \% \end{aligned}$$

- Note that 0.696788 was calculate in part (b).
- Errors decrease when the points used are closer to the interpolated point.
- Errors decrease as the degree of the interpolating polynomial increases.

### Finite Divided Difference (FDD) Table

Finite divided differences used in the Newton's Interpolating Polynomials can be presented in a table form. This makes the calculations much simpler.

| Х              | f( )               | f[,]                                | f[,,]  | f[,,,]  |
|----------------|--------------------|-------------------------------------|--|---|
| ×o             | f(x <b>0</b> )     | f[x <sub>1</sub> , x <sub>0</sub> ] | f[x <sub>2</sub> , x <sub>1</sub> , x <sub>0</sub> ] | f[x <sub>3</sub> , x <sub>2</sub> , x <sub>1</sub> , x <sub>0</sub> ] |
| X <sub>1</sub> | $f(x_1)$           | f[x <sub>2</sub> , x <sub>1</sub> ] | f[x3, x2, x1]  |   |
| X <sub>2</sub> | f(x <sub>2</sub> ) | f[x3, x2]                           |  |   |
| X <sub>3</sub> | f(x <sub>3</sub> ) |                                     |  |   |

**Exercise 27:** The first two columns of the following table is given. Calculate the missing finite divided differences.

| х   | f( ) f [ , ] |   | f[,,] | f[,,,] |
|-----|--------------|---|-------|--------|
| 4   | 0.6020600    | ? | ?     | ?      |
| 4.5 | 0.6532125    | ? | ?     |        |
| 5.5 | 0.7403627    | ? |       |        |
| 6   | 0.7781513    |   |       |        |

• The numbers decrease as we go right in the table. This means that the contribution of higher order terms are less than the lower order terms.

• This is expected. The opposite behavior is an indication of an inappropriate interpolation (see exam questions of Fall 2006).

#### Example 30:

| х   | f( )      | f[,]      | f[,,]      | f[,,,]   |
|-----|-----------|-----------|------------|----------|
| 4   | 0.6020600 | 0.1023050 | -0.0101032 | 0.001194 |
| 4.5 | 0.6532125 | 0.0871502 | -0.0077153 |          |
| 5.5 | 0.7403627 | 0.0755772 |            |          |
| 6   | 0.7781513 |           |            |          |

Use this previously calculated table to interpolate for log(5).

(a) Using points x=4 and x=4.5.

log (5)  $\approx$  0.60206 + (5 - 4) 0.102305 = 0.704365  $\epsilon_t = 0.8 \%$  (this is extrapolation)

(b) Using points x=4.5 and x=5.5.

 $\log (5) \approx 0.6532125 + (5 - 4.5) \ 0.0871502 = 0.696788 \qquad \epsilon_t = 0.3 \ \%$ 

(c) Using points x=4 and x=6.

The entries of the above table can not be used for this interpolation.

(d) Using points x=4.5, x=5.5 and x=6.

 $\log (5) \approx 0.6532125 + (5-4.5) \ 0.0871502 + (5-4.5)(5-5.5)(-0.0077153) = 0.698717 \quad \varepsilon_t = 0.04 \ \%$ 

(e) Using all four points.

 $\log (5) \approx 0.60206 + (5 - 4) \ 0.102305 + (5 - 4)(5 - 4.5)(-0.0101032) \\ + (5 - 4)(5 - 4.5)(5 - 5.5)(0.001194) = 0.6990149 \qquad \epsilon_{t} = 0.006 \ \%$ 

### Exercise 28:

|   | Х  | f( )      |
|---|----|-----------|
|   | -2 | -0.909297 |
|   | -1 | -0.841471 |
|   | 0  | 0.000000  |
| • | 1  | 0.841471  |
| • | 3  | 0.141120  |
|   | 4  | -0.756802 |
|   | 6  | -0.279415 |

Create the FDD table for the given data set. Use it to interpolate for f(2).

• For a linear interpolation use the points x=1 and x=3.

• For a quadratic interpolation either use the points x=0, x=1 and x=3 or the points x=1, x=3 and x=4.

• For a third cubic interpolation use the points x=0, x=1, x=3 and x=4.

**Important:** Always try to put the interpolated point at the center of the points used for the interpolation.

**Exercise 29:** Complete the following table given for the log function. Do you observe anything strange? Comment.

| Х   | f( ) | f[,] | f[,,] | f[,,,] | f[,,,,] | f[,,,,,] |
|-----|------|------|-------|--------|---------|----------|
| 0.5 |      |      |       |        |         |          |
| 1   |      |      |       |        |         |          |
| 3   |      |      |       |        |         |          |
| 5   |      |      |       |        |         |          |
| 8   |      |      |       |        |         |          |
| 10  |      |      |       |        |         |          |

### Errors of Newton's DD Interpolating Polynomials

$$f_{n}(x) = f(x_{0}) + (x - x_{0}) f[x_{1}, x_{0}] + (x - x_{0})(x - x_{1}) f[x_{2}, x_{1}, x_{0}] + \dots$$
  
+  $(x - x_{0})(x - x_{1}) \cdots (x - x_{n-1}) f[x_{n}, x_{n-1}, \dots, x_{1}, x_{0}]$ 

- The structure of Newton's Interpolating Polynomials is similar to the Taylor series.
- Remainder (truncation error) for the Taylor series was  $R_n = \frac{f^{n+1}(\xi)}{(n+1)!}(x_{i+1} x_i)^{n+1}$
- Similarly the remainder for the n<sup>th</sup> order interpolating polynomial is

$$R_{n} = \frac{f^{n+1}(\xi)}{(n+1)!} (x - x_{0})(x - x_{1}) \dots (x - x_{n})$$

where  $\xi$  is somewhere in the interval containing the interpolated point x and other data points.

- But usually only the set of data points is given and the function f is not known.
- An alternative formulation uses a finite divided difference to approximate the (n+1)<sup>th</sup> derivative.

$$R_n \approx f[x, x_n, x_{n-1}, ..., x_0](x - x_0)(x - x_1)...(x - x_n)$$

- But this includes f(x) which is not known.
- Error can be predicted if an additional data point  $(x_{n+1})$  is available

$$R_n \approx f[x_{n+1}, x_n, x_{n-1}, ..., x_0](x - x_0)(x - x_1)...(x - x_n)$$

which is nothing but  $f_{n+1}(x) - f_n(x)$ 

### Newton's Interpolating Polynomials for Equally Spaced Data

• If the data points are equally spaced and in ascending order, that is,

$$(x_0, y_0)$$
,  $(x_0 + h, y_1)$ ,  $(x_0 + 2h, y_1)$ , ...,  $(x_0 + nh, y_n)$ 

finite divided difference simplify.

$$f[x_{1}, x_{0}] = \frac{f(x_{1}) - f(x_{0})}{x_{1} - x_{0}} = \frac{\Delta f(x_{0})}{h}$$

$$f[x_{2}, x_{1}, x_{0}] = \frac{\frac{f(x_{2}) - f(x_{1})}{x_{2} - x_{1}} - \frac{f(x_{1}) - f(x_{0})}{x_{1} - x_{0}}}{x_{2} - x_{0}} = \frac{f(x_{2}) - 2f(x_{1}) + f(x_{0})}{2h^{2}} = \frac{\Delta f^{2}(x_{0})}{2h^{2}}$$
or in general  $f[x_{n}, x_{n-1}, ..., x_{0}] = \frac{\Delta f^{n}(x_{0})}{n! h^{n}}$ 

where  $\Delta f^{n}(x_{0})$  is the n<sup>th</sup> forward difference.

• With this notation Newton's DD Interpolating polynomials simplify to

$$f_{\mathbf{n}}(\mathbf{x}) = f(\mathbf{x}_{\mathbf{0}}) + \Delta f(\mathbf{x}_{\mathbf{0}}) \alpha + \Delta^{2} f(\mathbf{x}_{\mathbf{0}}) \alpha(\alpha - 1) / 2! + \ldots + \Delta^{\mathbf{n}} f(\mathbf{x}_{\mathbf{0}}) \alpha(\alpha - 1) \cdots (\alpha - n + 1) / n! + R_{\mathbf{n}}$$

where  $\alpha = (\mathbf{x} - \mathbf{x_0}) / h$  and  $R_n = f^{(n+1)}(\xi) h^{n+1} \alpha(\alpha - 1) \cdots (\alpha - n) / (n+1)!$ 

• This is called the forward Newton-Gregory formula.

### Lagrange Interpolating Polynomials

• It is a reformulation of Newton's Interpolating Polynomials.

$$f_n(x) = \sum_{i=0}^n L_i(x)f(x_i) \quad \text{where} \quad L_i(x) = \prod_{\substack{j=0 \ j \neq i}}^n \frac{x - x_j}{x_i - x_j}$$

• For n=1 (linear): 
$$f_1(x) = \frac{x - x_1}{x_0 - x_1} f(x_0) + \frac{x - x_0}{x_1 - x_0} f(x_1)$$

• For n=2: 
$$f_2(x) = \frac{(x-x_1)(x-x_2)}{(x_0-x_1)(x_0-x_2)}f(x_0) + \frac{(x-x_0)(x-x_2)}{(x_1-x_0)(x_1-x_2)}f(x_1) + \frac{(x-x_0)(x-x_1)}{(x_2-x_0)(x_2-x_1)}f(x_2)$$

- To generalize,  $n^{th}$  order polynomial is the summation of  $(n+1) n^{th}$  order polynomials.
- Each of these n<sup>th</sup> order polynomials have a value of 1 at one of the data points and have values of 0 at all other data points.
- This is due to the following property of Lagrange functions  $L_i(x) = \begin{cases} 1 & at x = x_i \\ 0 & at all other data points \end{cases}$



### Example 31:

| х | f(x)  |
|---|-------|
| 1 | 4.75  |
| 2 | 4.00  |
| 3 | 5.25  |
| 5 | 19.75 |
| 6 | 36.00 |

Calculate f(4) using Lagrange Interpolating Polynomials

(a) of order 1

(b) of order 2

(c) of order 3

(a) Linear interpolation. Select  $x_0 = 3$ ,  $x_1 = 5$   $f_1(x) = L_0(x) f(x_0) + L_1(x) f(x_1) = (x-5)/(3-5) 5.25 + (x-3)/(5-3) 19.75$  $f(4) \approx 12.5$ 

(b) Quadratic interpolation. Select  $x_0 = 2$ ,  $x_1 = 3$ ,  $x_1 = 5$   $f_2(x) = L_0(x) f(x_0) + L_1(x) f(x_1) + L_2(x) f(x_2)$  = (x-3)(x-5)/(2-3)(2-5) 4.00 + (x-2)(x-5)/(3-2)(3-5) 5.25 + (x-2)(x-3)/(5-2)(5-3) 19.75 $f(4) \approx 10.5$ 

**Exercise 30:** Solve part (b) using the last three points. Also solve part (c).

### **Spline Interpolation**

• We learned how to interpolate between n+1 data points using n<sup>th</sup> order polynomials.

• For high number of data points (typically n > 6 or 7), high order polynomials are necessary, but sometimes they suffer from oscillatory behavior.



• Instead of using a single high order polynomial that passes through all data points, we can use different lower order polynomials between each data pair.

- These lower order polynomials that pass through only two points are called splines.
- Third order (cubic) splines are the most preferred ones.



#### **Linear Splines:**

• Given a set of ordered data points, each two point can be connected using a straight line.



$$\begin{split} f(x) &= f(x_0) + m_0(x - x_0) & \text{for } x_0 \leq x \leq x_1 \\ f(x) &= f(x_1) + m_1(x - x_1) & \text{for } x_1 \leq x \leq x_2 \\ f(x) &= f(x_2) + m_2(x - x_2) & \text{for } x_2 \leq x \leq x_3 \end{split}$$

where the slopes are  $m_i = [f(x_{i+1}) - f(x_i)] / (x_{i+1} - x_i)$ 

• Functions are not continuous at the interior points.

#### **Quadratic Splines:**

• Every pair of data points are connected using quadratic functions.



- For n+1 data points, there are n splines and 3n unknown constants.
- We need 3n equations to solve for them.

#### **Quadratic Splines (cont'd):**

- These 3n equations are
  - The first and last functions must pass through the end points (2 equations).

$$a_1 x_0^2 + b_1 x_0 + c_1 = f(x_0)$$
  
 $a_n x_n^2 + b_n x_n + c_n = f(x_n)$ 

• The function values must be equal at interior points (2n-2 equations).

 $\begin{array}{c} a_{i-1} x_{i-1}^2 + b_{i-1} x_{i-1} + c_{i-1} = f(x_{i-1}) \\ a_i x_{i-1}^2 + b_i x_{i-1} + c_i = f(x_{i-1}) \end{array}$  for i = 2 to n

• First derivatives must be equal at the interior points (n-1 equations).

$$2 a_{i-1} x_{i-1} + b_{i-1} = 2 a_i x_{i-1} + b_i$$
 for i = 1 to n

• This makes a total of 3n-1 equations. One more equation is necessary and we need to make an arbitrary choice. Among many possibilities we will use the following,

• Take the second derivative at the first point to be zero (1 equation).



i.e. first two points are connected with a straight line.

• Solve this set of 3n linear algebraic equations with any of the methods that we learned.

### **Cubic Splines:**

• For n+1 points, there will be n intervals and for each interval there will be a 3<sup>rd</sup> order polynomial

 $a_i x_i^3 + b_i x_i^2 + c_i x + d_i$  for i = 1 to n

- Totally there are 4n unknowns. They can be solved using the following equations
  - The first and last functions must pass through the end points (2 equations).
  - The function values must be equal at interior points (2n-2 equations).
  - First derivatives must be equal at the interior points (n-1 equations).
  - Second derivatives must be equal at the interior points (n-1 equations).
  - This makes a total of 4n-2 equations. Two extra equations are (other choices are possible)
  - Second derivatives at the end points are zero (2 equations).

• Setting up and solving 4n equations is costly. There is another way of constructing cubic splines that results in only n-1 equations in n-1 unknowns. See pages 502-503 of the book.

#### Example 32:



• There are 5 points and n=4 splines. Totally there are 3n=12 unknowns. Equations are

- End points:  $a_1 1^2 + b_1 1 + c_1 = 1$  ,  $a_4 4^2 + b_4 4 + c_4 = 2$
- Interior points:  $a_1 2^2 + b_1 2 + c_1 = 5$  ,  $a_2 2^2 + b_2 2 + c_2 = 5$  $a_2 2.5^2 + b_2 2.5 + c_2 = 7$ ,  $a_3 2.5^2 + b_3 2.5 + c_3 = 7$

$$a_3 3^2 + b_3 3 + c_3 = 8$$
 ,  $a_4 3^2 + b_4 3 + c_4 = 8$ 

• Derivatives at the interior points:  $2a_12 + b_1 = 2a_22 + b_2$ 

$$2a_2 2.5 + b_2 = 2a_3 2.5 + b_3$$
  
 $2a_3 3 + b_3 = 2a_4 3 + b_4$ 

• Arbitrary choice for the missing equation:  $a_1 = 0$ 

#### Example 32 (cont'd):

•  $a_1=0$  is already known. Solve for the remaining 11 unknowns.

| <b>1</b> | 1 | 0          | 0   | 0 | 0    | 0   | 0 | 0  | 0  | 0 | $\left[ \mathbf{b_1} \right]$ |       | (1) |                             | ( <b>b</b> <sub>1</sub> ) |          | (4)  |   |
|----------|---|------------|-----|---|------|-----|---|----|----|---|-------------------------------|-------|-----|-----------------------------|---------------------------|----------|------|---|
| 0        | 0 | 0          | 0   | 0 | 0    | 0   | 0 | 16 | 4  | 1 | <b>C</b> <sub>1</sub>         |       | 2   |                             | <b>C</b> <sub>1</sub>     |          | -3   |   |
| 2        | 1 | 0          | 0   | 0 | 0    | 0   | 0 | 0  | 0  | 0 | $ \mathbf{a}_2 $              |       | 5   |                             | a <sub>2</sub>            |          | 0    |   |
| 0        | 0 | 4          | 2   | 1 | 0    | 0   | 0 | 0  | 0  | 0 | <b>b</b> <sub>2</sub>         |       | 5   |                             | <b>b</b> <sub>2</sub>     |          | 4    |   |
| 0        | 0 | 6.25       | 2.5 | 1 | 0    | 0   | 0 | 0  | 0  | 0 | <b>C</b> <sub>2</sub>         |       | 7   |                             | <b>c</b> <sub>2</sub>     |          | -3   |   |
| 0        | 0 | 0          | 0   | 0 | 6.25 | 2.5 | 1 | 0  | 0  | 0 | $\{\mathbf{a}_3\}$            | > = < | 7   | $\rightarrow$ $\rightarrow$ | { <b>a</b> <sub>3</sub>   | \<br>= · | -4   | ł |
| 0        | 0 | 0          | 0   | 0 | 9    | 3   | 1 | 0  | 0  | 0 | b <sub>3</sub>                |       | 8   |                             | b <sub>3</sub>            |          | 24   |   |
| 0        | 0 | 0          | 0   | 0 | 0    | 0   | 0 | 9  | 3  | 1 | <b>C</b> <sub>3</sub>         |       | 8   |                             | <b>C</b> <sub>3</sub>     |          | - 28 |   |
| 1        | 0 | <b>- 4</b> | -1  | 0 | 0    | 0   | 0 | 0  | 0  | 0 | a₄                            |       | 0   |                             | a₄                        |          | -6   |   |
| 0        | 0 | 5          | 1   | 0 | - 5  | -1  | 0 | 0  | 0  | 0 | b₄                            |       | 0   |                             | b₄                        |          | 36   |   |
| 0        | 0 | 0          | 0   | 0 | 6    | 1   | 0 | -6 | -1 | 0 | <b>c</b> <sub>4</sub>         |       | 0   |                             | <b>c</b> <sub>4</sub>     |          | 46   |   |

• Equations for the splines are

1<sup>st</sup> spline: f(x) = 4x - 3 (Straight line.)

2<sup>nd</sup> spline: f(x) = 4x - 3 (Same as the 1<sup>st</sup>. Coincidence)

3<sup>rd</sup> spline:  $f(x) = -4x^2 + 24x - 28$ 

4<sup>th</sup> spline:  $f(x) = -6x^2 + 36x - 46$ 

• To predict f(3.4) use the 4<sup>th</sup> spline.  $f(3.4) = -6 (3.4)^2 + 36 (3.4) - 46 = 7.04$ To predict f(2.2) use the 2<sup>nd</sup> spline. f(2.2) = 4 (2.2) - 3 = 5.8