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ignature.

## Read before you start:

- There are four questions.
- $\bullet\,$  The examination is closed-book.
- No computer/calculator is allowed.
- The duration of the examination is 100 minutes.
- Besides correctness, the CLARITY of your presentation will also be graded.

Q1	$\mathbf{Q2}$	$\mathbf{Q3}$	$\mathbf{Q4}$	Total

For each of the below dynamics determine whether the system has a periodic orbit.

(a) 
$$\begin{cases} \dot{x}_1 = -x_2 + x_1(1 - 2x_1^2 - 3x_2^2) \\ \dot{x}_2 = x_1 \end{cases}$$
 (b) 
$$\begin{cases} \dot{x}_1 = x_2 - x_1(1 - 2x_1^2 - 3x_2^2) \\ \dot{x}_2 = -x_1 \end{cases}$$

Consider the system

$$\dot{x}_1 = (x_1x_2 - 1)x_1^3 + (x_1x_2 - 1 + x_2^2)x_1$$
  
 $\dot{x}_2 = -x_2$ .

- (a) Show that the set  $\{x \in \mathbb{R}^2 : x_1x_2 \geq 2\}$  is forward invariant.
- (b) Find all the equilibrium points of this system.
- (c) Study the stability of each equilibrium point.
- (d) Does this system have a GAS equilibrium point?

Consider the second order system

$$\dot{x} = A\nabla V(x)$$

where  $A \in \mathbb{R}^{2 \times 2}$  and  $V : \mathbb{R}^2 \to \mathbb{R}$  is a continuously differentiable, positive definite function whose gradient satisfies  $\nabla V(x) \neq 0$  for all  $x \neq 0$ . For each of the following cases study the stability of the origin of this system.

(a) 
$$A = \begin{bmatrix} -2 & 1 \\ 1 & -2 \end{bmatrix}$$
 (b)  $A = \begin{bmatrix} 1 & -2 \\ 2 & 1 \end{bmatrix}$  (c)  $A = \begin{bmatrix} 0 & -2 \\ 2 & 0 \end{bmatrix}$ 

**(b)** 
$$A = \begin{bmatrix} 1 & -2 \\ 2 & 1 \end{bmatrix}$$

$$\mathbf{(c)} \quad A = \left[ \begin{array}{cc} 0 & -2 \\ 2 & 0 \end{array} \right]$$

For each of the below systems study the stability of the origin.

(a) 
$$\begin{cases} \dot{x}_1 = x_1 + x_2 \\ \dot{x}_2 = x_1^3 - x_2^3 \end{cases}$$
 Hint: Consider  $V(x) = \frac{1}{4}x_1^4 - \frac{1}{2}x_2^2$ .

**(b)** 
$$\begin{cases} \dot{x}_1 = -x_1 - x_2 \\ \dot{x}_2 = x_1^3 \end{cases}$$
 *Hint: Consider*  $V(x) = \frac{1}{4}x_1^4 + \frac{1}{2}x_2^2$ .

(c) 
$$\begin{cases} \dot{x}_1 = -x_1^3 - x_2 \\ \dot{x}_2 = x_1^3 - x_2 |x_2| \end{cases}$$
 Hint: Consider  $V(x) = \frac{1}{4}x_1^4 + \frac{1}{2}x_2^2$ .