

**First name:**\_\_\_\_\_**Last name:**\_\_\_\_\_**Student ID:**\_\_\_\_\_**Signature:**\_\_\_\_\_**Read before you start:**

- There are four questions.
- The examination is closed-book.
- No computer/calculator is allowed.
- The duration of the examination is 100 minutes.
- Besides correctness, the CLARITY of your presentation will also be graded.

Q1	Q2	Q3	Q4	Total

**Q1.**

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Consider the nonlinear system

$$\begin{aligned}\dot{x}_1 &= x_2 \\ \dot{x}_2 &= -x_1 - x_2 + x_2^2.\end{aligned}$$

- (a) Obtain its linearization  $\dot{\eta} = A\eta$  at the origin.
- (b) Find a quadratic Lyapunov function  $V : \mathbb{R}^2 \rightarrow \mathbb{R}$  that satisfies (for the linear system)  $\dot{V}(\eta) = -\|\eta\|^2$ .
- (c) Using this  $V$  show that the origin of the nonlinear system is exponentially stable.
- (d) Find a positive number  $c$  for which the set  $\{x \in \mathbb{R}^2 : V(x) \leq c\}$  is forward invariant with respect to the nonlinear system.

**Q2.**

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Suppose the system  $\dot{x} = f(x)$  satisfies the Lipschitz condition  $\|f(x) - f(y)\| \leq L\|x - y\|$  for some (fixed)  $L > 0$  and all  $x, y \in \mathbb{R}^n$ . Furthermore, suppose the origin is an equilibrium point. Using the function  $V(x) = 0.5\|x\|^2$  and the comparison lemma, show that this system does not exhibit finite escape times.

**Q3.**

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Consider the second-order system

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x_1^3 \\ x_2^3 \end{bmatrix}.$$

Investigate the stability properties of the origin with respect to the parameter  $\theta \in [0, 2\pi)$ . That is, find the ranges of  $\theta$  for which the origin is stable, asymptotically stable, and unstable. Justify your answer. *Hint: You may want to use  $V(x) = 0.25x_1^4 + 0.25x_2^4$ .*

**Q4.**

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$$\text{(a)} \begin{cases} \dot{x}_1 &= x_2 \\ \dot{x}_2 &= -\frac{x_1}{1+x_1^2} \end{cases} \qquad \text{(b)} \begin{cases} \dot{x}_1 &= x_2 \\ \dot{x}_2 &= -\frac{x_1}{1+x_1^2} - x_2^3 \end{cases}$$

For each of the above systems answer the following questions.

- (i) Does the system have periodic orbits? Does it have limit cycles? Explain.
- (ii) Is the origin stable? Is it asy. stable? Is it globally asy. stable? Explain.

*Hint:*  $\int_0^{x_1} \frac{z}{1+z^2} dz = \frac{1}{2} \ln(1+x_1^2).$