First name:
Last name:
Student ID:
Signatura

Read before you start:

- There are four questions.
- $\bullet\,$ The examination is open-book.
- No computer/calculator is allowed.
- $\bullet\,$ The duration of the examination is 150 minutes.
- Besides correctness, the CLARITY of your presentation will also be graded.

Q1	$\mathbf{Q2}$	Q3	Q4	Total

 $\mathbf{Q1.}$

Consider the second-order system below.

$$\dot{x}_1 = x_2 - ax_1$$

$$\dot{x}_2 = -x_1^3 - bx_2 + u$$

$$y = x_2$$

For each of the following cases using the storage function candidate $V(x) = (x_1^4 + 2x_2^2)/4$ determine whether the system is lossless, output strictly passive, or strictly passive. Moreover, investigate the stability properties of the origin of the unforced (u=0) system.

- a) When a = 0 and b = 0.
- **b)** When a = 0 and b > 0.
- c) When a > 0 and b > 0.

 $\mathbf{Q2}$.

Consider the below second-order systems.

System (1):
$$\begin{cases} \dot{x}_1 = x_2 \\ \dot{x}_2 = -x_1^3 + u_1 \\ y_1 = x_2 \end{cases}$$
 System (2):
$$\begin{cases} \dot{x}_3 = x_4 \\ \dot{x}_4 = -x_3^3 + u_2 \\ y_2 = x_4 \end{cases}$$

Let $u = [u_1 \ u_2]^T$ and $y = [y_1 \ y_2]^T$ and $x = [x_1 \ x_2 \ x_3 \ x_4]^T$. Suppose we couple these systems by letting u = -Qy + v, where Q is a symmetric positive definite matrix.

- a) Show that the map from v to y is finite-gain \mathcal{L}_2 stable. What is the gain?
- b) Show that when v = 0 the origin x = 0 is globally asymptotically stable.

 $\mathbf{Q3.}$

Consider the Henon map

$$x_1^+ = x_2 + 1 - ax_1^2$$

$$x_2^+ = bx_1$$

$$y = h(x)$$

where a and b are nonzero constants. For this system find the observer dynamics $\hat{x}^+ = g(\hat{x}, y)$ by applying Glad's method for each of the below cases.

- a) When $h(x) = x_1$.
- **b)** When $h(x) = x_2$.

 $\mathbf{Q4.}$

Let

$$A = \left[\begin{array}{cc} -2 & -4 \\ 1 & 2 \end{array} \right]$$

- a) Determine the stability properties of the origin of the system $x^+ = Ax$.
- b) Find a symmetric positive definite matrix P satisfying the discrete-time Lyapunov equation $A^T P A P + I = 0$. Hint: What is A^2 ?
- c) Show that the origin of the system $x^+ = Ax + \varepsilon ||x||B$, where $B \in \mathbb{R}^{2\times 1}$ is a constant matrix and $\varepsilon > 0$, is asymptotically stable for small enough ε . Hint: Try $V(x) = x^T P x$.