

First name:_____**Last name:**_____**Student ID:**_____**Signature:**_____**Read before you start:**

- There are four questions.
- The examination is open-book.
- No computer/calculator is allowed.
- The duration of the examination is 150 minutes.
- PLEASE EXPLAIN ALL YOUR ANSWERS.

Q1	Q2	Q3	Q4	Total

Q1.

Consider the following system.

$$\begin{aligned}\dot{x} &= \begin{bmatrix} 3 & -4 & 0 \\ 2 & -3 & 0 \\ 1 & 0 & 2 \end{bmatrix} x + \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} u \\ y &= [0 \ 1 \ 0] x.\end{aligned}$$

- (a) Is this system controllable?
- (b) Is this system observable?
- (c) Can we stabilize this system by state feedback $u = -Kx$?
- (d) Can we asymptotically estimate the state of this system by an observer?
- (e) Is this system BIBO stable?

Q2.

Consider the following system.

$$\begin{aligned}\dot{x} &= \begin{bmatrix} \alpha & 8 \\ -4 & \beta \end{bmatrix} x + \begin{bmatrix} 2 \\ 1 \end{bmatrix} u \\ y &= [4 \quad -1] x.\end{aligned}$$

It is known that this system is observable and BIBO stable. Also, for some initial condition $x(0) = \eta$ and zero input $u = 0$, the output is measured to be $y(t) = 9e^t$.

(a) Find α and β .

(b) Find η .

Q3.

Let $\{v_1, v_2, \dots, v_n\}$ be an orthonormal basis for \mathbb{R}^n , that is, $v_i^T v_i = 1$ and $v_i^T v_j = 0$ for $i \neq j$. Define $A := v_1 v_2^T + v_2 v_1^T$.

- (a) Write $\text{range}(A)$.
- (b) Write $\text{null}(A)$.
- (c) Determine the minimal polynomial of A . *Hint:* $A^3 = ?$
- (d) Find all the eigenvalues of A .
- (e) Find all the eigenvectors of A .

- (f) Write the Jordan form of A .
- (g) Compute e^{At} .
- (h) Compute A^k .
- (i) Determine the stability of $\dot{x} = Ax$.
- (j) Determine the stability of $x^+ = Ax$.

Q4.

Theorem. *Let $A, P \in \mathbb{R}^{n \times n}$ and $C \in \mathbb{R}^{m \times n}$. Suppose (C, A) is observable, $P^T = P > 0$, and the Lyapunov equality $A^T P A - P = -C^T C$ holds. Then the system $\dot{x} = Ax$ is exp. stable.*

Proof. ?