PLEASE WRITE YOUR NAME CLEARLY USING CAPITAL LETTERS		
FULL NAME	STUDENT ID	DURATION
		150 MINUTES
4 QUESTIONS ON 4 PAGES	TOTAL 100 POINTS	

By signing below, I pledge that I will write this examination as my own work and without the assistance of others or the usage of unauthorized material or information. I understand that possession of any kind of electronic device during the exam is prohibited. I also understand that not obeying the rules of the examination will result in immediate cancellation and disciplinary procedures.

Signature .....

 $(10 \times 6 \ pts)$  1. Consider the set  $\mathbb{R}^{\mathbb{R}} = \{f \mid f : \mathbb{R} \to \mathbb{R} \text{ is a function}\}$  of all functions on  $\mathbb{R}$ . Then  $\mathbb{R}^{\mathbb{R}}$  is a vector space over  $\mathbb{R}$ , where the vector addition f + g and the scalar multiplication  $\alpha \cdot f$  are defined as follows.

$$(f+g)(x) = f(x) + g(x)$$
 and  $(\alpha \cdot f)(x) = \alpha f(x)$  for every  $x \in \mathbb{R}$ 

for every  $\alpha \in \mathbb{R}$  and  $f, g \in \mathbb{R}^{\mathbb{R}}$ .

(a) Determine whether or not  $W = \{ f \in \mathbb{R}^{\mathbb{R}} \mid \exists x \in \mathbb{R} \ f(x) = 0 \}$  is a subspace of  $\mathbb{R}^{\mathbb{R}}$ .

Set f(x) = |x| and g(x) = |x - 1|. Then we have  $f, g \in W$ , however,  $f + g \notin W$  since  $(f + g)(x) = |x| + |x - 1| \neq 0$  for any  $x \in \mathbb{R}$ . Therefore, W is not closed under vector addition and hence is not a subspace.

Set  $S = {\sin(x), \cos(x), e^{2x}} \subseteq \mathbb{R}^{\mathbb{R}}$ . In Part (b),(c), (d) and (e), we shall together show that S is linearly independent.

(b) Complete the following statement appropriately: S is linearly independent iff for every  $\alpha, \beta, \gamma \in \mathbb{R}$ , we have

$$\alpha \cdot \sin(x) + \beta \cdot \cos(x) + \gamma \cdot e^{2x} = 0$$
 for every  $x \in \mathbb{R}$  implies that  $\alpha = \beta = \gamma = 0$ 

(c) In the equation that you wrote in Part (a), by plugging in  $x = -\pi, 0, \pi/2$  respectively, you shall obtain a linear system consisting of three equations in variables  $\alpha$ ,  $\beta$  and  $\gamma$ . Complete the entries of the following matrix A so that it is the coefficient matrix of this linear system.

$$A = \begin{pmatrix} 0 & -1 & e^{-2\pi} \\ 0 & 1 & 1 \\ 1 & 0 & e^{\pi} \end{pmatrix}$$

(d) Find det(A).

Applying the column expansion formula on the first column, we get

$$\det(A) = (-1)^{1+1} \cdot 0 \cdot \det\begin{pmatrix} 1 & 1 \\ 0 & e^{\pi} \end{pmatrix} + (-1)^{2+1} \cdot 0 \cdot \det\begin{pmatrix} -1 & e^{-2\pi} \\ 0 & e^{\pi} \end{pmatrix} + (-1)^{3+1} \cdot 1 \cdot \det\begin{pmatrix} -1 & e^{-2\pi} \\ 1 & 1 \end{pmatrix} = -1 - e^{-2\pi}$$

(e) Without applying Gaussian elimination, argue that the linear system AX = Y in Part (c) has the unique solution  $\alpha = \beta = \gamma = 0$ .

Observe that the column matrix Y is the zero column matrix because the constant term in the equation in Part (b) is 0. Since  $det(A) \neq 0$ , we have that A is invertible and consequently, the linear system  $AX = \mathbf{0}$  has only the trivial solution  $\alpha = \beta = \gamma = 0$  as  $X = A^{-1}\mathbf{0} = \mathbf{0}$ .

Having shown that S is linearly independent, consider the subspace  $V = \langle S \rangle$  spanned by the set S. Then  $S = \{\sin(x), \cos(x), e^{2x}\}$  is an ordered basis for V. In Part (f), (g), (h), (i) and (j), consider V as a separate vector space on its own.

(f) You are given that the differentiation map  $D: V \to V$  given by D(f) = f' is a linear transformation. Find its matrix  $[D]_S$  relative to the ordered basis S.

Observe that 
$$[D(\sin(x))]_S = [\cos(x)]_S = \begin{bmatrix} 0\\1\\0 \end{bmatrix}$$
 and  $[D(\cos(x))]_S = [-\sin(x)]_S = \begin{bmatrix} -1\\0\\0 \end{bmatrix}$   
and  $[D(e^{2x})]_S = [2e^{2x}]_S = \begin{bmatrix} 0\\0\\2 \end{bmatrix}$ . Hence we have  $[D]_S = \begin{bmatrix} 0 & -1 & 0\\1 & 0 & 0\\0 & 0 & 2 \end{bmatrix}$ 

(g) Let  $U: V \to V$  be a linear transformation such that  $[U]_S = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$ . Find  $U(2\sin(x) + 6\cos(x) + e^{2x})$ .

$$\begin{bmatrix} U(2\sin(x) + 6\cos(x) + e^{2x}) \end{bmatrix}_S = \begin{bmatrix} U \end{bmatrix}_S \cdot [2\sin(x) + 6\cos(x) + e^{2x}]_S = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 6 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 9 \\ 1 \end{bmatrix}$$
  
and so  $U(2\sin(x) + 6\cos(x) + e^{2x}) = 2\sin(x) + 9\cos(x) + e^{2x}.$ 

Recall that every element of V is of the form  $\alpha \cdot \sin(x) + \beta \cdot \cos(x) + \gamma \cdot e^{2x}$ . (h) Consider the linear functional  $\varphi : V \to \mathbb{R}$  given by  $\varphi(f) = f(0)$ . Describe the subspace ker( $\varphi$ ) in the set-builder notation using an equality only involving  $\alpha$ ,  $\beta$  or  $\gamma$ .

$$\ker(\varphi) = \left\{ \alpha \cdot \sin(x) + \beta \cdot \cos(x) + \gamma \cdot e^{2x} \in V \mid \beta + \gamma = 0 \right\}$$

(i) Find a basis for  $\ker(\varphi)$ . Since  $\varphi$  is a non-zero functional, its image is a non-zero subspace of  $\mathbb{R}$  and hence equals  $\mathbb{R}$ , from which it follows that  $\operatorname{rank}(\varphi) = 1$ . Since we have  $\operatorname{rank}(\varphi) + \operatorname{nullity}(\varphi) = \dim_{\mathbb{R}}(V) = 3$  by the rank-nullity theorem, we obtain that  $\operatorname{nullity}(\varphi) = 2$ . Therefore, any subset of  $\ker(\varphi)$  that consists of two linearly independent vectors will form a basis for  $\ker(\varphi)$ . Consider  $\mathcal{B} = \{\sin(x), \cos(x) - e^{2x}\}$ . Then  $\mathcal{B} \subseteq \ker(\varphi)$  because  $\varphi(\sin(x)) = \sin(0) = 0$  and  $\varphi(\cos(x) - e^{2x}) = \cos(0) - e^0 = 0$ . Moreover, if  $\mathcal{B}$  were linearly dependent, then S would be linearly dependent. Thus  $\mathcal{B}$  is linearly independent and consequently, is a basis for  $\ker(\varphi)$ .

For the next part of the question, consider  $\mathbb{R}^3$  as a vector space over  $\mathbb{R}$  together with its standard operations.

(j) Find an isomorphism  $T: V \to \mathbb{R}^3$  such that the image of ker $(\varphi)$  under T is equal to the xy-plane  $\{(x, y, z) \in \mathbb{R}^3 \mid z = 0\}$  and  $T(e^{2x}) = (0, 0, 1)$ .

$$T\left(\alpha \cdot \sin(x) + \beta \cdot \cos(x) + \gamma \cdot e^{2x}\right) = (\alpha, \beta, \beta + \gamma)$$

For this part of the question, you need not check that the map T that you define is a linear transformation, however, you need to check that it has the other desired properties. Let T be defined as above. Then, by the definition of T, we have that  $T(\sin(x)) = (1,0,0)$  and  $T(\cos(x) - e^{2x}) = (0,1,0)$  and  $T(e^{2x}) = (0,0,1)$ . Moreover the subspace

$$\langle (1,0,0), (0,1,0) \rangle = \langle T(\sin(x)), T(\cos(x) - e^{2x}) \rangle = T\left( \langle \sin(x), \cos(x) - e^{2x} \rangle \right) = T\left( \ker(\varphi) \right)$$

equals the xy-plane.

Observe that  $T(\alpha \cdot \sin(x) + \beta \cdot \cos(x) + \gamma \cdot e^{2x}) = (\alpha, \beta, \beta + \gamma) = (0, 0, 0)$  iff  $\alpha = \beta = \gamma = 0$  and hence  $\ker(T) = \{0\}$  is the trivial subspace consisting of the zero function. It follows that T is injective. However, since  $\dim_{\mathbb{R}} V = \dim_{\mathbb{R}} \mathbb{R}^3 = 3$  and T is injective, T is also surjective. Therefore, T is an isomorphism.

(10 pts) 2. Let  $n \ge 2$  be an integer and  $A \in M_{n \times n}(\mathbb{Z})$ . Suppose that each entry of A is an odd integer. Show that det(A) is an even integer.

Recall that  $\det(A) = \sum_{\varphi \in S_n} \operatorname{sgn}(\varphi) \prod_{i=1}^n A_{i\varphi(i)}$ . Since each entry of A is an odd integer, the term  $\operatorname{sgn}(\varphi) \prod_{i=1}^n A_{i\varphi(i)}$  is odd for every  $\varphi \in S_n$  being a product of odd integers. But then, since  $|S_n| = n!$  is even, being a sum of even number many odd integers,  $\det(A)$  is even. Alternatively, this fact can be proven by induction on n using the column/row expansion formula of determinant.

(6+6+6 pts) 3. In this question, we shall work over the field  $\mathbb{F} = \mathbb{Z}_3 = \{0, 1, 2\}$  with three elements. Consider the matrix  $M = \begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}$  over the field  $\mathbb{Z}_3$ .

(a) If exists, find the inverse  $M^{-1}$  using Gaussian elimination.

$$\begin{pmatrix} 1 & 1 & 0 & 1 & | & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & | & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & | & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 & | & 0 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{2R_2 + R_1 \to R_1} \begin{pmatrix} 1 & 0 & 0 & 0 & | & 1 & 2 & 0 & 0 \\ 0 & 1 & 0 & 1 & | & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & | & 0 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_3 + R_4 \to R_4} \begin{pmatrix} 1 & 0 & 0 & 0 & | & 1 & 2 & 0 & 0 \\ 0 & 1 & 0 & 1 & | & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 & | & 0 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_3 + R_4 \to R_4} \begin{pmatrix} 1 & 0 & 0 & 0 & | & 1 & 2 & 0 & 0 \\ 0 & 0 & 2 & 0 & | & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & | & 0 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{2R_4 + R_2 \to R_2} \begin{pmatrix} 1 & 0 & 0 & 0 & | & 1 & 2 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 & 2 & 2 \\ 0 & 0 & 2 & 0 & | & 0 & 0 & 1 & 1 \end{pmatrix} \xrightarrow{2R_3 \to R_3} \begin{pmatrix} 1 & 0 & 0 & 0 & | & 1 & 2 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 & 1 \end{pmatrix} \text{ and so } M^{-1} = \begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & 1 & 2 & 2 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

(b) Find the determinant det(M).

Observe that, in the row reduction process above, we only applied the row operation of "multiplying a row by a constant and adding it to another row" until we obtained the matrix

$$N = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Since this row operation does not change the determinant, we have that  $det(M) = det(N) = 1 \cdot 1 \cdot 2 \cdot 1 = 2$ . Alternatively, one may find det(M) using a row/column expansion formula.

(c) Find the adjoint matrix adj(M) without computing any determinants except det(M).

Since  $M^{-1} = (\det(M))^{-1} \operatorname{adj}(M)$ , we have that

$$\operatorname{adj}(M) = \operatorname{det}(M)M^{-1} = 2\begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & 1 & 2 & 2 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 1 & 0 & 0 \\ 0 & 2 & 1 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 2 & 2 \end{bmatrix}$$

<u>(6+6 pts)</u> 4. For the parts of this question, which were asked as midterm questions during the semester, no partial credit will be given unless the answer is completely correct. (a) Let V be a vector space over  $\mathbb{R}$  with a basis  $\mathcal{B}$ . Suppose that the set

$$\mathcal{B} + \mathcal{B} = \{b_1 + b_2 : b_1, b_2 \in \mathcal{B}\}$$

is also a basis for V. Prove that  $\dim_{\mathbb{R}}(V)$  is equal to either 0 or 1.

This question was already asked in a past midterm and its solution was already posted.

(b) Find an example of a vector space W over the field  $\mathbb{R}$  and a **non-zero** linear transformation  $T: W \to W$  such that ker(T) is isomorphic to W. For this part of the question, it is sufficient to define W and  $T: W \to W$  explicitly without proving that they are as desired.

This question was already asked in a past midterm and its solution was already posted.