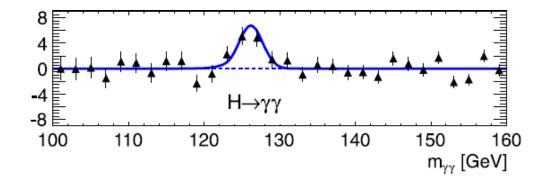


Introduction to Statistical Data Analysis

Chapter 4
Monte Carlo
Methods



Jan 2024

Introduction

The deterministic systems are described by some mathematical rule. But some systems are not deterministic known as random or stochastic. **The Monte Carlo Method** is a numerical technique for calculating probabilities and related quantities by using sequences of random numbers.

Pioneers

https://en.wikipedia.org



Enrico Fermi



Stanislaw Ulam



J. von Neumann



N. Metropolis

Some Applications

MC method is often used to simulate experimental data.

Applications Field Example

Physics Simulation of Radioactive decay

Engineering Tolerance Analysis

Bioinformatics Protein Folding

Statistics Distribution Functions

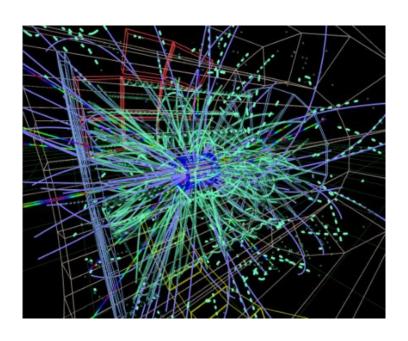
Economy Modelling Stock Exchange

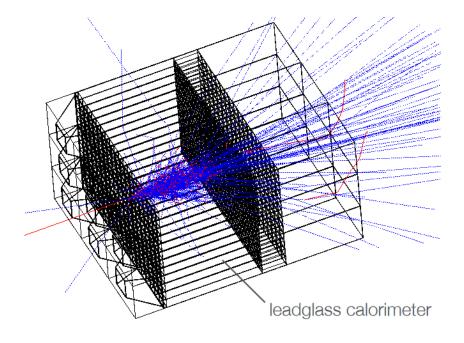
Medicine Treatment Planning in Radiation Therapy

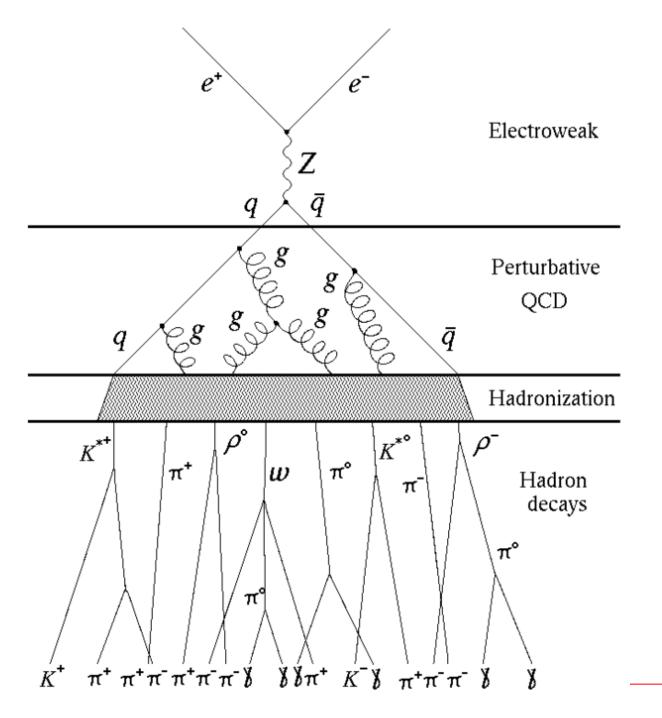
In Particle Physics

Simulation of experimental data is typically done in two stages:

- 1. Event generation (Pythia, Sherpa, Herwig, ...)
- 2. Detector simulation (GEANT4)







Random Numbers

In principle, the best way to obtain a series of random numbers:

$$\{X_1, X_2, X_3, ..., X_n\}$$

is to use some process in nature:



- Throw a coin or dice
- Lotto results of last Sunday.
- Number of particles from radioactive decay in every 1 min.
- Number of cosmic muons falling on 10cm x 20 cm area in 10 s.
- Brightness level of a star observed in atmoshpere in every 1 s.

These are not very efficient.

Therefore, random number generator algorithms have been developed to be used in computers.

Uniformly Distributed Random Numbers

Linear Conguential Method (1948)

uses 32-bit integers have a period of at most $2^{31} \sim 10^9$.

The method is employed by an equation of the form:

$$X_{i+1} = (a X_i + b) \mod m$$

where mod means modulo. Constants *a*, *b* and *m* are chosen carefully such that the sequence of numbers becomes chaotic and evenly distributed. The resulting values are therefore more correctly called **pseudorandom**.

RULES:

- First initial number, x_0 , called seed, is selected.
- $m > x_0, a, b ≥ 0$
- The range of values is 0 to *m*. The period generator is *m-1*.
- Divide by m to convert to 0. to 1.

Example 1

if we select $a = b = x_0 = 7$ and m = 10 results in the squence:

$$x = \{7, 6, 9, 0, 7, 6, 9, 0, ...\}$$

and dividing each number by 10 gives:

$$r = \{0.7, 0.6, 0.9, 0.0, 0.7, 0.6, 0.9, 0.0, \dots\}$$

very poor!

Some good generators are proposed:

- IBM in 1960: $x_{i+1} = (69069 x_i) \mod 2^{31}-1$
- Park and Miller: $x_{i+1} = (16807 x_i) \mod 2^{31}-1$
- P.L. L'Ecuyer: $x_{i+1} = (40692 x_i) \mod 2147483399$

Some advanced algorithms:

- RANLUX has period of 10¹⁴³ (Root uses this algorithm)
- Mersenne twister has period of 10⁶⁰⁰⁰

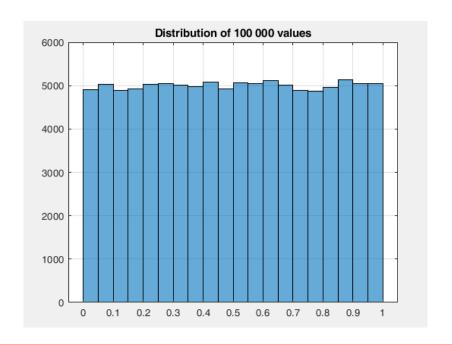
Example 2: Implementation of RANDU

```
m = 2^31-1; % maximum value
x = 314; % the seed

for i = 1:10
    x = mod(69069*x, m); % integer
    r = x / m; % real
    disp(r)
```

end

OUTPUT 0.0101 0.5352 0.6915 0.3512 0.5424 0.8728 0.6736 0.2940 0.4968 0.9160



Uniformly Distributed Random Numbers

Assume that *r* is a uniform random real number in the range [0,1]

A and B are real numbers,

M and N are integer numbers, then the value

$$X = A + (B-A)r$$

will be <u>random real number</u> in the range [A, B]

$$x = M + int(Nr)$$

will be <u>random integer number</u> in the range [M,N].

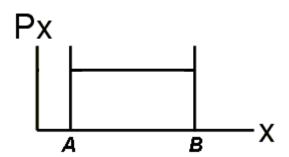


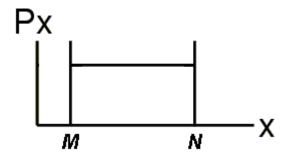
Random decay angle in the range $[0, 2\pi]$

$$phi = 2*pi*r;$$

Random integer in the range [1, 6]

$$D = 1 + int(6*r);$$





Built-in Random Number Generators

C++

```
https://cplusplus.com/reference/random/
```

Obsolete C++

```
int k = rand(); returns random integer in the range [0, RAND_MAX]
double r = double(k)/RAND_MAX;
```

Root

```
TRandom rnd;
double = rnd.Uniform(); returns random real in the range (0,1).
```

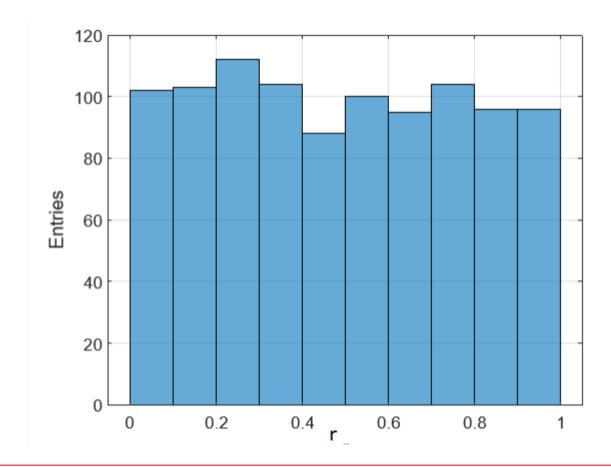
MATLAB

```
r = rand returns random real in the range (0,1).

r = rand(3,2) generates random 3x2 random matrix.
```

Example 3: Using rand function

```
n = 1000;
r = rand(n,1);
histogram(r,10)
xlabel('r')
ylabel('Entries')
grid on
```



Box-Muller Algorithm for S.N.D.

- 1. Generate two uniformly distributed random numbers u_1 and u_2 in the range [0,1]
- 2. Set

$$\phi = 2\pi u_1, \qquad r = \sqrt{-2 \ln u_2}$$

3. Then

$$z_1 = r \cos \phi$$
 and $z_2 = r \sin \phi$

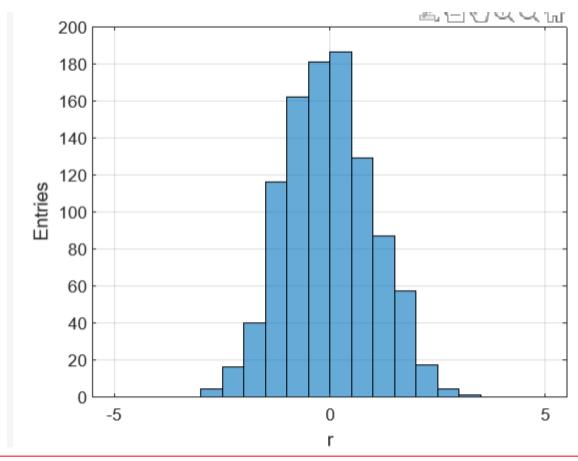
are two independent rv's following a standard normal distribution

To get a random number taken from standard normal distribution:

- use function normrnd(0,1) in MATLAB.
- use function rnd.Gaus (0,1) in Root.

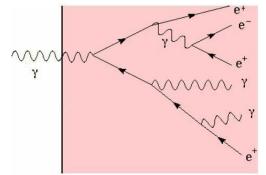
Example 4: using normrnd function

```
n = 1000;
r = normrnd(0,1, n,1);
histogram(r,12)
xlabel('r')
ylabel('Entries')
grid
```



Example 5: ECAL Detector Resolution

Photon energy measured, E, is proportional to number of electrons, n, which are counted in the ECAL shower, because the number of charges is related with energy deposition in any space. Thus: $E \propto n$. But, this counting is a statistical process carrying a statistical uncertainty $\sigma_E \propto \sqrt{n}$. Then,

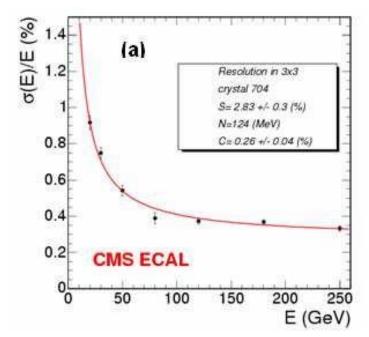


$$\frac{\sigma_E}{E} \propto \frac{\sqrt{n}}{n} = \frac{1}{\sqrt{n}}$$

or

$$\frac{\sigma_E}{E} = \frac{R}{\sqrt{n}}$$

for ATLAS $R = 0.10 \text{ GeV}^{1/2}$ for CMS $R = 0.05 \text{ GeV}^{1/2}$

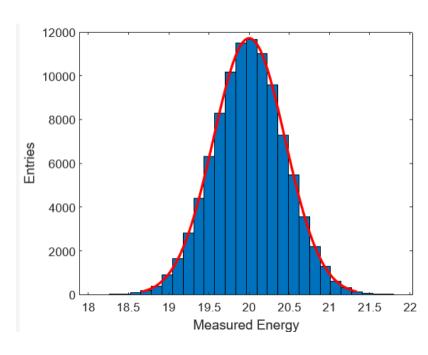


We can model ECAL by smearing the photon energies (E is in GeV).

$$\sigma_E = 0.1\sqrt{E}$$

For example, assume that E = 20 GeV. Then, the following code block can roughly simulate the response of ATLAS ECAL for $n = 100\,000$ photons.

```
E = 20;
sigmaE = 0.1*sqrt(E);
n = 1e5;
energy = normrnd(E,sigmaE,n,1);
histfit(energy,30)
xlabel('Measured Energy')
ylabel('Entries')
```

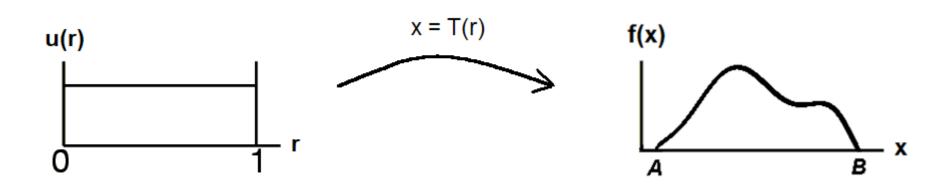


Random Distributions

In simulations of random processes, we often require a non-uniform distribution of random numbers. Two standard methods are:

- The Transformation Method
- The Rejection Method

The aim of both these methods is to convert a uniform distribution of random numbers of the form u(r) into a non-uniform distribution of the form f(x). The values of x can then be treated as simulated measurements



Transformation Method (Continues RV)

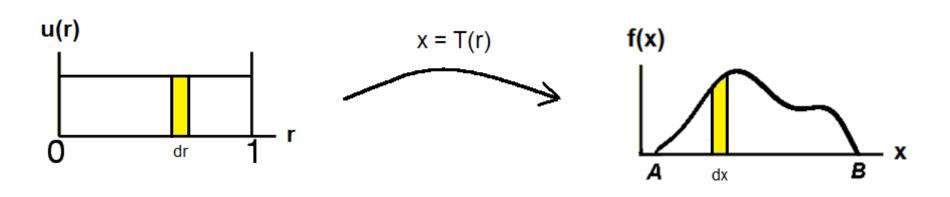
Let u(r) be uniform distribution in the range [0,1].

Consider a distribution f(x) from which we want to draw random numbers, x.

Conservation of random numbers!

$$u(r)dr = f(x)dx$$

The aim is to find a transformation function x = T(r) such that the distribution of random variable x is f(x).



Since u(r) = 1, we need to solve D.E.

$$dr = f(x)dx$$
$$r = \int f(x)dx$$

Right hand side is CDF:

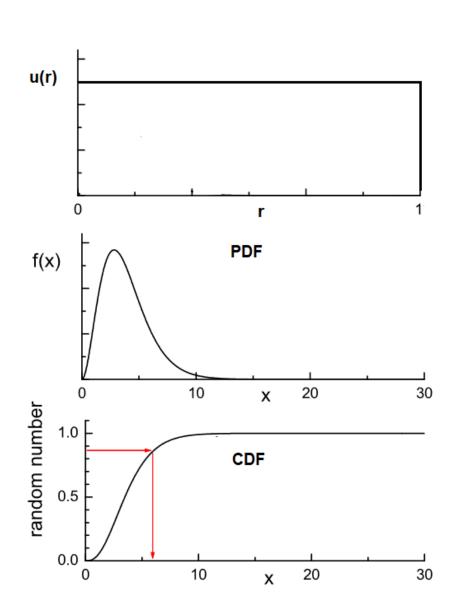
$$F(x) = \int_{-\infty}^{x} f(x)dx = \int_{0}^{r} u(r)dr = r$$

$$F(x) = r$$

We want to get x from inverse CDF.

$$x = F^{-1}(r) = T(r)$$

This function is known as the **Transformation Function.**



Example 6

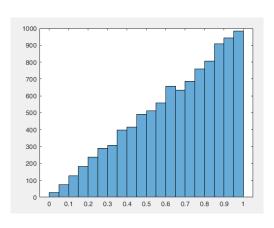
We want a random distibution function

$$f(x) = 2x \quad [0 < x < 1]$$

Then we can find the transformation function

T(r) as follows:

$$r = \int 2x dx = x^2$$
 => $x = \sqrt{r} = T(r)$



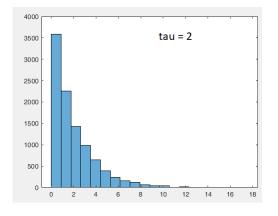
We want a random distibution function

$$f(t) = \frac{1}{\tau} e^{-t/\tau}$$
 [0 < t < \infty]

Transformation function:

$$r = \int f(t)dt = 1 - e^{-t/\tau} =>$$

 $t = -\tau \ln(1 - r) = -\tau \ln(r) = T(r)$



- In MATLAB, we use exprnd(tau)
 exprnd(2) returns single value with mean 2
 exprnd(2,5,1) returns 5x1 matrix (array)
- In Root, we use double Exp(double tau)
 rnd.Exp(2) returns single value with mean 2

Example 7: Uniform point on a sphere

$$\frac{\mathrm{d}p}{\mathrm{d}\Omega} = \frac{\mathrm{d}p}{\sin\theta\,\mathrm{d}\theta\,\mathrm{d}\phi} = \mathrm{const} \equiv k \qquad \qquad \frac{\mathrm{d}p}{\mathrm{d}\theta\,\mathrm{d}\phi} = k\sin\theta \equiv f(\phi)g(\theta)$$

Distributions for θ and ϕ :

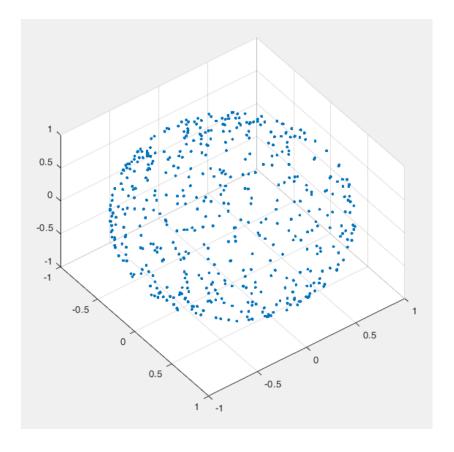
$$f(\phi) \equiv rac{\mathrm{d}p}{\mathrm{d}\phi} = \mathrm{const} = rac{1}{2\pi}, \qquad 0 \leq \phi \leq 2\pi$$
 $g(heta) \equiv rac{\mathrm{d}p}{\mathrm{d} heta} = rac{1}{2}\sin heta, \qquad 0 \leq heta \leq \pi$

Calculating the inverse of the cumulative distribution we obtain:

$$\phi=2\pi r_1$$
 $heta=rccos(1-2r_2)$ $ext{[as }G(heta)=rac{1}{2}(1-\cos heta) ext{]}$

Upshot: ϕ and $\cos \theta$ need to be distributed uniformly

```
n = 500;
R = 1;
phi = 2*pi*rand(n,1);
theta = acos(1-2*rand(n,1));
x = R*sin(theta).*cos(phi);
  = R*sin(theta).*sin(phi);
z = R*cos(theta);
plot3(x,y,z,'.')
grid
```



Transformation Method (Discrete RV)

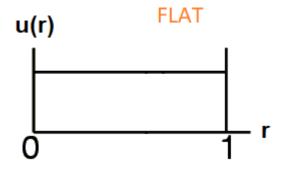
Suppose **X** can take on *n* distinct values $\mathbf{X} = \{x_1, x_2, x_3, \dots x_n\}$ with

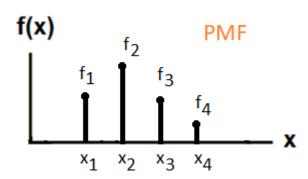
PDF:
$$f(x) = \{f_1, f_2, f_3, ..., f_n\}$$
 and

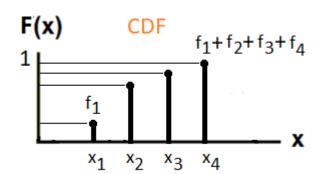
CDF:
$$F(x) = \{f_1, f_1 + f_2, \dots, f_1 + f_2 + f_3 + \dots + f_n\}$$

Then to generate a sample value of X

- **1.** Generate uniform ranfom number *r* in the range [0, 1].
- 2. for j = 1 to n Set $\mathbf{X} = x_j$ if $F_{j-1} < r \le F_j$ end





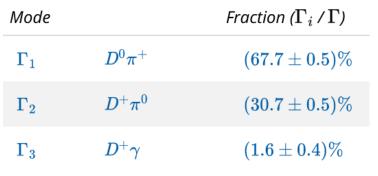


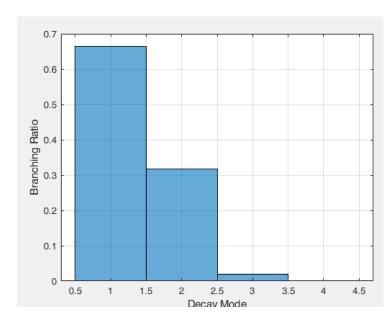
Example 8: Branching Ratio

D*± decays into 3 different channels.

Select a decay mode randomly.

```
% decay mode #
x = [1 \ 2 \ 3];
f = [0.677 \ 0.307 \ 0.016]; % BR
F = [0.677 \ 0.984 \ 1.000]; % CDF
N = 1000;
                % Look at 1000 decays
X = zeros(N,1);
for i = 1:N
    r = rand:
    for j = 1:3
        if j==1 && r <= F(j)</pre>
           X(i) = x(j);
        elseif j > 1 \&\& r > F(j-1) \&\& r \le F(j)
           X(i) = x(j);
        end
    end
```





```
end
```

```
histogram(X,3,'BinEdges',0.5:4.5,'Normalization','pdf')
xlabel('Channel')
ylabel('Branching Ratio')
grid on
```

Rejection Method

The Transformation Method is useful when the function T(r) can easly be evaluated. However, there are cases when desired distribution may not be known in analytic form.

Two examples are as follows:

Gaussian fuction : $f(x) = e^{-x^2}$

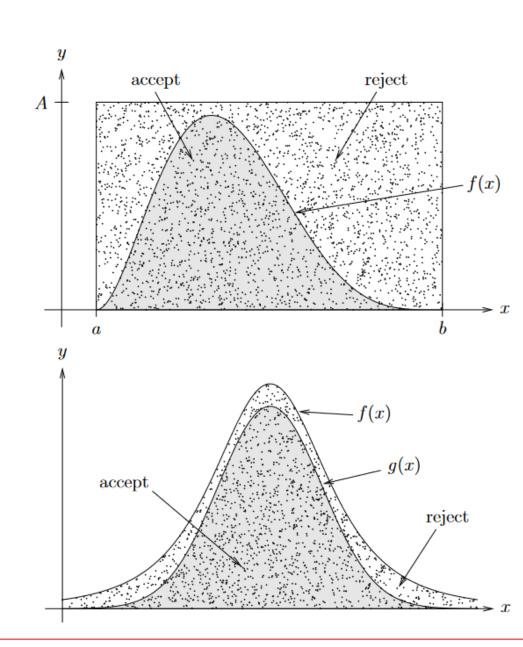
Quadratic function : $f(x) = 1 + x^2$

Such problems can be handled with algorithm known as **Rejection Method.**

It has the advantage of being able to create a distribution for any function.

Rejection Method

- Algorithm
 - Generate random number x uniformly between a and b
 - Generate second random y number uniformly between 0 and A
 - Accept x if y < f(x)
 - Repeat many times
- The efficiency of this algorithm can be quite small
- Improvement possible by choosing a majorant, i.e., a function which encloses g(x) and whose integral is known ("importance sampling")



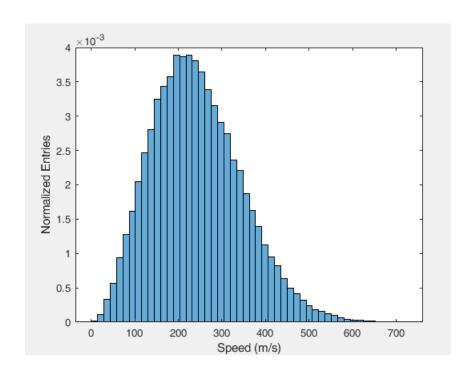
Example 9: Maxwell Distribution in C++

```
double Maxwell Boltzman(double m, double T) {
  // Returns, for an atom of mass m (kg) and temperature T (K),
  // a velocity in m/s which is randomly selected from
  // a Maxwell-Boltzman Distribution function using Rejection Method.
  double const kB = 1.38e-23;
  double kT = kB*T;
  double C = M PI*sqrt(2.0) * pow(m/(M PI*kT),1.5);
  double vp = sqrt(2.0*kT/m);
  double vmin = 0.0;
  double vmax = 10*vp;
  double fmax = C * vp*vp * exp(-1.0), Ptest, fmb;
   // Rejection algorithm
   while (1)
                                                        f(v) = \left[rac{m}{2\pi kT}
ight]^{rac{3}{2}} 4\pi v^2 \exp\!\left(-rac{mv^2}{2kT}
ight)
     double r = rnd.Uniform();
     double v = rnd.Uniform();
     Ptest = fmax*r;
           = vmin + (vmax-vmin)*v;
           = C * v*v * exp(-0.5*m*v*v/kT);
     fmb
     if (fmb > Ptest) return v;
```

Example 9: Maxwell Distribution in Matlab

```
clear:
T = 300; % K, room temperature
m = 1.8e-25; % kg, mass of silver atom
kB = 1.38e-23; % Boltzman constant
   = kB*T:
kТ
    = pi*sqrt(2.0) * (m/(pi*kT))^1.5;
С
     = sqrt(2.0*kT/m); % peak velocity
vmin = 0.0;
vmax = 20*vp;
fmax = C * vp*vp * exp(-1.0);
    = 100000; % number of random numbers
    = zeros(n,1);
for i = 1:n
    % Rejection algorithm
    while 1
      Ptest = fmax*rand;
            = vmin + (vmax-vmin) *rand;
            = C * v*v * exp(-0.5*m*v*v/kT);
      fmb
      if fmb > Ptest
          break:
      end
    end
    r(i) = v; % random value from function
end
histogram(r,50,'Normalization','pdf')
xlabel('Speed (m/s)')
ylabel('Normalized Entries')
```

$$f(v) = \left[rac{m}{2\pi kT}
ight]^{rac{3}{2}} 4\pi v^2 \exp\!\left(-rac{mv^2}{2kT}
ight)$$



Monte Carlo Integration

Naïve Monte Carlo integration:

uniform distribution
$$\int_{a}^{b} f(x) dx = (b-a) \int_{a}^{b} f(x) u(x) dx = (b-a) \langle f(x) \rangle \approx (b-a) \cdot \frac{1}{n} \sum_{i=1}^{n} f(x_i)$$

$$=: I$$

$$=: \hat{I}$$

Typical Error (Standard deviation)
$$\sigma[I] = \frac{b-a}{\sqrt{n}}\sigma[f]$$

Not efficient in 1D integrals. Very good at higher dimensions.

Exercise: Find volume of the intersection of a cone and a torus

- Hard to solve analytically
- ► Easy to solve by scattering points homogeneously inside a cuboid containing the intersect.

x_i: uniformly distributed

Example 10:

Evaluate the following integrals via MC integration method.

(a)
$$\int_0^{\pi} \sin(x) dx = 2.0$$

(b) $\int_0^{2\pi} \int_0^{\pi} \sin(\theta) d\theta d\phi = 4\pi \approx 12.5664$

```
% solution of (b)
% solution of (a)
n = 10000;
                                 n = 10000;
s = 0;
                                 s = 0;
for i=1:n
                                 for i=1:n
                                     theta = pi*rand;
   x = pi*rand;
    f = sin(x);
                                     phi = 2*pi*rand;
    s = s + f;
                                     f = sin(theta);
end
                                     s = s + f;
inteq = (pi-0) * s/n
                                 end
                                 integ = (2*pi-0)*(pi-0) * s/n
```

Example 11: Estimating π using MC

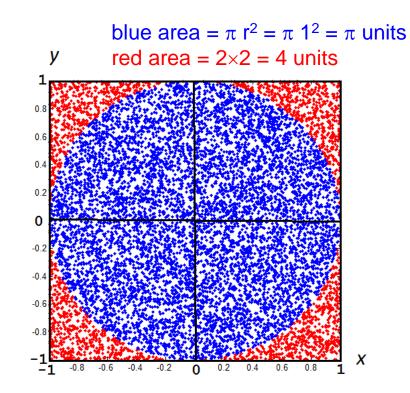
Populate a square with *n* randomly-placed points [the blue and red points]

$$-1.0 \le x < +1.0$$

 $-1.0 \le y < +1.0$

Count the number of points m that lie inside a circle of unit Radius [the blue points] then $m / n \approx \pi / 4 \implies \pi \approx 4 m / n$

```
n = 100000;
x = 2*rand(n,1)-1;
y = 2*rand(n,1)-1;
m = sum(x.^2 + y.^2 < 1);
disp(4*m/n)
```



Convergence:

n	
10 ³	3.1 68
10 ⁴	3.1 692
10 ⁵	3.14 836
10 ⁶	3.14 0310
10 ⁷	3.141 9192
π	3.1415927

Some Applications

- Modelling Cherenkov Radiation Photons http://www1.gantep.edu.tr/~bingul/zemax/src/cherenkov.m
- 2. Simulation of Two-Body Decay http://www1.gantep.edu.tr/~bingul/simulation/twoBody
- 3. Simulation of Stern-Gerlach Experiment http://www1.gantep.edu.tr/~bingul/seminar/spin
- 4. Simulation of Fussion Chain Reaction http://www1.gantep.edu.tr/~bingul/simulation/fission/
- 5. Tolerance Analysis of a Lens See Section 9.3 at: http://www1.gantep.edu.tr/~bingul/ep208/latex/ep208_LectureNotes.pdf
- 6. Predicting Potential Energy Function in Schrödinger Equation via MC coming soon ...

References

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