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> # Prof. Dr. Serkan Dağ
# ME 451 Introduction to Composite Structures
> # File 7.5
# Example on maximum in-plane shear stiffness
> restart:
with(LinearAlgebra):
> # Enter the number of plies
> n := 4:
> # Define extensional, coupling, and bending stiffness matrices
> A := Matrix(3):
B := Matrix(3):
Dm := Matrix(3):
> # Define ply surface coordinate vector in meters
# h is denoted by h0

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$$h := \begin{bmatrix} -\frac{h_0}{2} \\ -\frac{h_0}{4} \\ 0 \\ \frac{h_0}{4} \\ \frac{h_0}{2} \end{bmatrix};$$

$$h := \begin{bmatrix} -\frac{1}{2} h_0 \\ -\frac{1}{4} h_0 \\ 0 \\ \frac{1}{4} h_0 \\ \frac{1}{2} h_0 \end{bmatrix} \quad (1)$$

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> # Define ply angle vector in radians
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$$\theta := \begin{bmatrix} \text{the} \\ -\text{the} \\ -\text{the} \\ \text{the} \end{bmatrix};$$

(2)

$$\theta := \begin{bmatrix} \text{the} \\ -\text{the} \\ -\text{the} \\ \text{the} \end{bmatrix} \quad (2)$$

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> # Define Qbar array
Qbar := Array(1..3, 1..3, 1..n) :
ArrayNumElems(Qbar);
36
> # Enter properties of the unidirectional lamina
# From Table 2.1 for graphite/epoxy (unit = MPa)
> EI := 181000 :
E2 := 10300 :
nu12 := 0.28 :
G12 := 7170 :
> # Calculate elements of the compliance matrix for the
unidirectional lamina
> S11 :=  $\frac{1}{EI}$  :
S12 :=  $-\frac{\nu_{12}}{EI}$  :
S22 :=  $\frac{1}{E2}$  :
S66 :=  $\frac{1}{G12}$  :
> # Calculate elements of the reduced stiffness matrix for the
unidirectional lamina
> Q11 :=  $\frac{S22}{S11 \cdot S22 - S12^2}$  :
Q22 :=  $\frac{S11}{S11 \cdot S22 - S12^2}$  :
Q12 :=  $-\frac{S12}{S11 \cdot S22 - S12^2}$  :
Q66 :=  $\frac{1}{S66}$  :
> # Calculate elements of transformed reduced stiffness matrix for
each angle lamina
# Unit = MPa
> for i from 1 by 1 to n
while true do
  Qbar[1, 1, i] := Q11  $\cdot (\cos(\theta[i, 1]))^4 + Q22 \cdot (\sin(\theta[i, 1]))^4 + 2 \cdot (Q12 + 2 \cdot Q66)$ 
     $\cdot (\cos(\theta[i, 1]))^2 \cdot (\sin(\theta[i, 1]))^2$  :
  Qbar[1, 2, i] :=  $(Q11 + Q22 - 4 \cdot Q66) \cdot (\sin(\theta[i, 1]))^2 \cdot (\cos(\theta[i, 1]))^2 + Q12$ 
     $\cdot ((\cos(\theta[i, 1]))^4 + (\sin(\theta[i, 1]))^4)$  :
  Qbar[1, 3, i] :=  $(Q11 - Q12 - 2 \cdot Q66) \cdot (\sin(\theta[i, 1])) \cdot (\cos(\theta[i, 1]))^3 - (Q22 - Q12$ 
     $- 2 \cdot Q66) \cdot (\sin(\theta[i, 1]))^3 \cdot \cos(\theta[i, 1])$  :

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$$Qbar[2, 2, i] := Q11 \cdot (\sin(\theta[i, 1]))^4 + Q22 \cdot (\cos(\theta[i, 1]))^4 + 2 \cdot (Q12 + 2 \cdot Q66) \cdot (\cos(\theta[i, 1]))^2 \cdot (\sin(\theta[i, 1]))^2;$$


$$Qbar[2, 3, i] := (Q11 - Q12 - 2 \cdot Q66) \cdot (\cos(\theta[i, 1])) \cdot (\sin(\theta[i, 1]))^3 - (Q22 - Q12 - 2 \cdot Q66) \cdot (\cos(\theta[i, 1]))^3 \cdot \sin(\theta[i, 1]);$$


$$Qbar[3, 3, i] := (Q11 + Q22 - 2 \cdot Q12 - 2 \cdot Q66) \cdot (\cos(\theta[i, 1]))^2 \cdot (\sin(\theta[i, 1]))^2 + Q66 \cdot ((\cos(\theta[i, 1]))^4 + (\sin(\theta[i, 1]))^4);$$

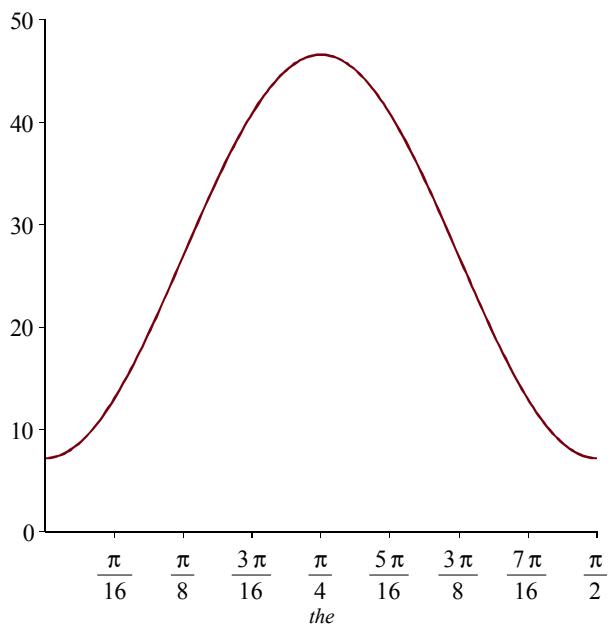

$$Qbar[2, 1, i] := Qbar[1, 2, i];$$


$$Qbar[3, 1, i] := Qbar[1, 3, i];$$


$$Qbar[3, 2, i] := Qbar[2, 3, i];$$

end do:
> # Calculate elements of extensional stiffness matrix [A], coupling stiffness matrix [B], and bending stiffness matrix [Dm]
# Units: [A]--> MPa.m; [B]--> MPa.m^2; [Dm]--> MPa.m^3
> for i from 1 by 1 to 3
  while true do
    for j from 1 by 1 to 3
      while true do
        A[i, j] := 0;
        B[i, j] := 0;
        Dm[i, j] := 0;
        for k from 1 by 1 to n
          while true do
            A[i, j] := A[i, j] + Qbar[i, j, k] \cdot (h[k+1, 1] - h[k, 1]);
            B[i, j] := B[i, j] +  $\frac{1}{2} \cdot Qbar[i, j, k] \cdot (h[k+1, 1]^2 - h[k, 1]^2);$ 
            Dm[i, j] := Dm[i, j] +  $\frac{1}{3} \cdot Qbar[i, j, k] \cdot (h[k+1, 1]^3 - h[k, 1]^3);$ 
          end do;
        end do;
      end do;
    end do;
  end do;
> # Astar (in 1/(MPa.m)) matrix
> Astar := MatrixInverse(A);
> # In-plane shear modulus in GPa
> Gxy :=  $\frac{1}{Astar[3, 3] \cdot h0} \cdot \frac{1}{1000};$ 
Gxy :=  $\frac{1}{1000} (6.713467205 \cdot 10^{12} \sin(\theta)^{12} + 1.814231637 \cdot 10^{14} \cos(\theta)^2 \sin(\theta)^{10}$  (4)
 $+ 5.223014410 \cdot 10^{14} \cos(\theta)^4 \sin(\theta)^8 + 6.951834900 \cdot 10^{14} \cos(\theta)^6 \sin(\theta)^6$ 
 $+ 5.223014405 \cdot 10^{14} \cos(\theta)^8 \sin(\theta)^4 + 1.814231636 \cdot 10^{14} \cos(\theta)^{10} \sin(\theta)^2$ 
 $+ 6.713467205 \cdot 10^{12} \cos(\theta)^{12}) / (9.36327365 \cdot 10^8 \sin(\theta)^8$ 
 $+ 2.838619439 \cdot 10^9 \cos(\theta)^2 \sin(\theta)^6 + 3.804584155 \cdot 10^9 \cos(\theta)^4 \sin(\theta)^4$ 
 $+ 2.838619439 \cdot 10^9 \cos(\theta)^6 \sin(\theta)^2 + 9.36327365 \cdot 10^8 \cos(\theta)^8)$ 
> plot(Gxy, theta = 0 ..  $\frac{\pi}{2}$ );

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> eq := diff(Gxy, the) :
fsolve(eq = 0, the = 0 .. Pi/2);
0.7853981636
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(5)

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> theta_max := evalf( 0.7853981636 * 180 / Pi );
theta_max := 44.99999998
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(6)

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> evalf( subs(the = Pi/4, Gxy) / subs(the = 0, Gxy) );
6.498028194
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(7)

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