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> # Prof. Dr. Serkan Dağ
  # ME 451 Introduction to Composite Structures
> # File 7.2
  # Example on failure loads of a laminate (cont'd)
> restart :
  with(LinearAlgebra) :
> # Enter the number of plies
> n := 3 :
> # Define extensional, coupling, and bending stiffness matrices
> A := Matrix(3) :
  B := Matrix(3) :
  Dm := Matrix(3) :
> # Define ply surface coordinate vector in meters
> h :=  $\begin{bmatrix} -\frac{7.5}{1000} \\ -\frac{2.5}{1000} \\ \frac{2.5}{1000} \\ \frac{7.5}{1000} \end{bmatrix}$  :
> # Define ply angle vector in radians
> theta :=  $\begin{bmatrix} 0 \\ \frac{\text{Pi}}{2} \\ 0 \end{bmatrix}$  :
> # Define Qbar array
  Qbar := Array(1..3, 1..3, 1..n) :
  ArrayNumElems(Qbar);

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> # Enter properties of the unidirectional lamina
  # From Table 2.1 for graphite/epoxy (unit = MPa)
> E1 := 181000 :
  E2 := 10300 :
  nu12 := 0.28 :
  G12 := 7170 :
> # Calculate elements of the compliance matrix for the
  unidirectional lamina
> S11 :=  $\frac{1}{E1}$  :
  S12 :=  $-\frac{\text{nu12}}{E1}$  :
  S22 :=  $\frac{1}{E2}$  :

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$$S66 := \frac{1}{G12} :$$

> # Calculate elements of the reduced stiffness matrix for the unidirectional lamina

$$Q11 := \frac{S22}{S11 \cdot S22 - S12^2} :$$

$$Q22 := \frac{S11}{S11 \cdot S22 - S12^2} :$$

$$Q12 := -\frac{S12}{S11 \cdot S22 - S12^2} :$$

$$Q66 := \frac{1}{S66} :$$

> # Calculate elements of transformed reduced stiffness matrix for each angle lamina

Unit = MPa

> for i from 1 by 1 to n
while true do

$$Qbar[1, 1, i] := Q11 \cdot (\cos(\text{theta}[i, 1]))^4 + Q22 \cdot (\sin(\text{theta}[i, 1]))^4 + 2 \cdot (Q12 + 2 \cdot Q66) \cdot (\cos(\text{theta}[i, 1]))^2 \cdot (\sin(\text{theta}[i, 1]))^2 :$$

$$Qbar[1, 2, i] := (Q11 + Q22 - 4 \cdot Q66) \cdot (\sin(\text{theta}[i, 1]))^2 \cdot (\cos(\text{theta}[i, 1]))^2 + Q12 \cdot ((\cos(\text{theta}[i, 1]))^4 + (\sin(\text{theta}[i, 1]))^4) :$$

$$Qbar[1, 3, i] := (Q11 - Q12 - 2 \cdot Q66) \cdot (\sin(\text{theta}[i, 1])) \cdot (\cos(\text{theta}[i, 1]))^3 - (Q22 - Q12 - 2 \cdot Q66) \cdot (\sin(\text{theta}[i, 1]))^3 \cdot \cos(\text{theta}[i, 1]) :$$

$$Qbar[2, 2, i] := Q11 \cdot (\sin(\text{theta}[i, 1]))^4 + Q22 \cdot (\cos(\text{theta}[i, 1]))^4 + 2 \cdot (Q12 + 2 \cdot Q66) \cdot (\cos(\text{theta}[i, 1]))^2 \cdot (\sin(\text{theta}[i, 1]))^2 :$$

$$Qbar[2, 3, i] := (Q11 - Q12 - 2 \cdot Q66) \cdot (\cos(\text{theta}[i, 1])) \cdot (\sin(\text{theta}[i, 1]))^3 - (Q22 - Q12 - 2 \cdot Q66) \cdot (\cos(\text{theta}[i, 1]))^3 \cdot \sin(\text{theta}[i, 1]) :$$

$$Qbar[3, 3, i] := (Q11 + Q22 - 2 \cdot Q12 - 2 \cdot Q66) \cdot (\cos(\text{theta}[i, 1]))^2 \cdot (\sin(\text{theta}[i, 1]))^2 + Q66 \cdot ((\cos(\text{theta}[i, 1]))^4 + (\sin(\text{theta}[i, 1]))^4) :$$

$$Qbar[2, 1, i] := Qbar[1, 2, i] :$$

$$Qbar[3, 1, i] := Qbar[1, 3, i] :$$

$$Qbar[3, 2, i] := Qbar[2, 3, i] :$$

end do

> # Calculate elements of extensional stiffness matrix [A], coupling stiffness matrix [B], and bending stiffness matrix [Dm]
Units: [A]--> MPa.m; [B]--> MPa.m^2; [Dm]--> MPa.m^3

> # Do not consider contributions from the 90-degree ply

> for i from 1 by 1 to 3
while true do

for j from 1 by 1 to 3

while true do

$$A[i, j] = 0 :$$

$$B[i, j] := 0 :$$

$$Dm[i, j] := 0 :$$

for k from 1 by 1 to n

while true do

if k = 2 then

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next
end if:
A[i,j] := A[i,j] + Qbar[i,j,k]·(h[k+1,1] - h[k,1]) :
B[i,j] := B[i,j] +  $\frac{1}{2}$ ·Qbar[i,j,k]·(h[k+1,1]2 - h[k,1]2) :
Dm[i,j] := Dm[i,j] +  $\frac{1}{3}$ ·Qbar[i,j,k]·(h[k+1,1]3 - h[k,1]3) :

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end do:
end do:
end do:

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> evalf( A );
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$$\begin{bmatrix} 1818.111388 & 28.96924444 & 0. \\ 28.96924444 & 103.4615873 & 0. \\ 0. & 0. & 71.70000000 \end{bmatrix} \quad (2)$$

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> evalf( B );
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$$\begin{bmatrix} 0. & 0. & 0. \\ 0. & 0. & 0. \\ 0. & 0. & 0. \end{bmatrix} \quad (3)$$

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> evalf( Dm );
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$$\begin{bmatrix} 0.04924051676 & 0.0007845837034 & 0. \\ 0.0007845837034 & 0.002802084656 & 0. \\ 0. & 0. & 0.001941875000 \end{bmatrix} \quad (4)$$

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> # Compute Astar matrix in 1/(MPa.m)
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> Astar := MatrixInverse( A );
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$$Astar := \begin{bmatrix} 5.525 \times 10^{-4} & -1.547 \times 10^{-4} & 0.000 \times 10^0 \\ -1.547 \times 10^{-4} & 9.709 \times 10^{-3} & 0.000 \times 10^0 \\ 0.000 \times 10^0 & 0.000 \times 10^0 & 1.395 \times 10^{-2} \end{bmatrix} \quad (5)$$

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> # Define load vector
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$$N := \begin{bmatrix} Nx \\ 0 \\ 0 \end{bmatrix};$$

$$N := \begin{bmatrix} Nx \\ 0 \\ 0 \end{bmatrix} \quad (6)$$

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> # Find strains (Note that strains in this case are equal to mid-plane strains)
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> Eps := Multiply( Astar, N );
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$$Eps := \begin{bmatrix} 5.5249 \times 10^{-4} Nx \\ -1.5470 \times 10^{-4} Nx \\ 0.0000 \times 10^0 \end{bmatrix} \quad (7)$$

> # Calculate global stresses in the 0-degree ply (n=1)

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> sigma1 := Qbar[1, 1, 1]·Eps[1, 1] + Qbar[1, 2, 1]·Eps[2, 1] + Qbar[1, 3, 1]·Eps[3, 1];
sigma1 := Qbar[2, 1, 1]·Eps[1, 1] + Qbar[2, 2, 1]·Eps[2, 1] + Qbar[2, 3, 1]·Eps[3, 1];
tauxy1 := Qbar[3, 1, 1]·Eps[1, 1] + Qbar[3, 2, 1]·Eps[2, 1] + Qbar[3, 3, 1]·Eps[3, 1];
sigma1 := 99.99999999 Nx
sigma1 := 0.
tauxy1 := 0.

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> # Calculate global stresses in the 0-degree ply (n=3)

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> sigma3 := Qbar[1, 1, 3]·Eps[1, 1] + Qbar[1, 2, 3]·Eps[2, 1] + Qbar[1, 3, 3]·Eps[3, 1];
sigma3 := Qbar[2, 1, 3]·Eps[1, 1] + Qbar[2, 2, 3]·Eps[2, 1] + Qbar[2, 3, 3]·Eps[3, 1];
tauxy3 := Qbar[3, 1, 3]·Eps[1, 1] + Qbar[3, 2, 3]·Eps[2, 1] + Qbar[3, 3, 3]·Eps[3, 1];
sigma3 := 99.99999999 Nx
sigma3 := 0.
tauxy3 := 0.

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> # Calculate local stresses in the 0-degree ply (n=1)

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> sigma11 := (cos(theta[1, 1]))2·sigma1 + (sin(theta[1, 1]))2·sigma1 + 2·sin(theta[1, 1])
·cos(theta[1, 1])·tauxy1;
sigma21 := (sin(theta[1, 1]))2·sigma1 + (cos(theta[1, 1]))2·sigma1 - 2·sin(theta[1, 1])
·cos(theta[1, 1])·tauxy1;
tau121 := -sin(theta[1, 1])·cos(theta[1, 1])·sigma1 + sin(theta[1, 1])·cos(theta[1, 1])
·sigma1 + ((cos(theta[1, 1]))2 - (sin(theta[1, 1]))2)·cos(theta[1, 1])·tauxy1;
sigma11 := 99.99999999 Nx
sigma21 := 0.
tau121 := 0.

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> # Calculate local stresses in the 0-degree ply (n=3)

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> sigma13 := (cos(theta[3, 1]))2·sigma3 + (sin(theta[3, 1]))2·sigma3 + 2·sin(theta[3, 1])
·cos(theta[3, 1])·tauxy3;
sigma23 := (sin(theta[3, 1]))2·sigma3 + (cos(theta[3, 1]))2·sigma3 - 2·sin(theta[3, 1])
·cos(theta[3, 1])·tauxy3;
tau123 := -sin(theta[3, 1])·cos(theta[3, 1])·sigma3 + sin(theta[3, 1])·cos(theta[3, 1])
·sigma3 + ((cos(theta[3, 1]))2 - (sin(theta[3, 1]))2)·cos(theta[3, 1])·tauxy3;
sigma13 := 99.99999999 Nx
sigma23 := 0.
tau123 := 0.

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> # Input strength values for graphite/epoxy lamina

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> sigma1Tult := 1500 :
sigma1Cult := 1500 :
sigma2Tult := 40 :
sigma2Cult := 246 :
tau12ult := 68 :

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> # Determine coefficients of Tsai-Wu failure criterion
> H1 :=  $\frac{1}{\sigma_{1Tult}} - \frac{1}{\sigma_{1Cult}}$  :
H2 :=  $\frac{1}{\sigma_{2Tult}} - \frac{1}{\sigma_{2Cult}}$  :
H11 :=  $\frac{1}{\sigma_{1Tult} \cdot \sigma_{1Cult}}$  :
H22 :=  $\frac{1}{\sigma_{2Tult} \cdot \sigma_{2Cult}}$  :
H12 :=  $-\frac{1}{2} \cdot \text{sqrt}\left(\frac{1}{\sigma_{1Tult} \cdot \sigma_{1Cult} \cdot \sigma_{2Tult} \cdot \sigma_{2Cult}}\right)$  :
> # Apply Tsai-Wu failure criterion for the 0-degree ply (n=1)
> eq1 := H1·sigma11 + H2·sigma21 + H11·sigma112 + H22·sigma212 + H66·tau1212 + 2·H12·sigma11
·sigma21;
solve(eq1 = 1, Nx);
eq1 := 0.00444444444444 Nx2
15.00000000, -15.00000000 (12)
> # Calculate mid-plane strain at this level of loading
> Nx := 15.00000000 :
epsx0 := Eps[1, 1];
epsx0 := 0.008287292820 (13)
>

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