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> # Prof. Dr. Serkan Dağ
# ME 451 Introduction to Composite Structures
> # File 6.3
# Example on computation of engineering constants of a symmetric
laminate
> restart :
with(LinearAlgebra) :
> # Enter the number of plies
> n := 3 :
> # Define extensional, coupling, and bending stiffness matrices
> A := Matrix(3) :
B := Matrix(3) :
Dm := Matrix(3) :
> # Define ply surface coordinate vector in meters
> h :=  $\begin{bmatrix} -\frac{7.5}{1000} \\ -\frac{2.5}{1000} \\ \frac{2.5}{1000} \\ \frac{7.5}{1000} \end{bmatrix}$  :
> # Define ply angle vector in radians
> theta :=  $\begin{bmatrix} 0 \\ \frac{\text{Pi}}{2} \\ 0 \end{bmatrix}$  :
> # Define Qbar array
Qbar := Array(1..3, 1..3, 1..n) :
ArrayNumElems(Qbar);
27
> # Enter properties of the unidirectional lamina
# From Table 2.1 for graphite/epoxy (unit = MPa)
> E1 := 181000 :
E2 := 10300 :
nu12 := 0.28 :
G12 := 7170 :
> # Calculate elements of the compliance matrix for the
unidirectional lamina
> S11 :=  $\frac{1}{E1}$  :
S12 :=  $-\frac{\text{nu12}}{E1}$  :

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$$S_{22} := \frac{1}{E_2} :$$

$$S_{66} := \frac{1}{G_{12}} :$$

> # Calculate elements of the reduced stiffness matrix for the unidirectional lamina

$$Q_{11} := \frac{S_{22}}{S_{11} \cdot S_{22} - S_{12}^2} :$$

$$Q_{22} := \frac{S_{11}}{S_{11} \cdot S_{22} - S_{12}^2} :$$

$$Q_{12} := -\frac{S_{12}}{S_{11} \cdot S_{22} - S_{12}^2} :$$

$$Q_{66} := \frac{1}{S_{66}} :$$

> # Calculate elements of transformed reduced stiffness matrix for each angle lamina

Unit = MPa

> for i from 1 by 1 to n
while true do

$$Q_{bar}[1, 1, i] := Q_{11} \cdot (\cos(\theta_{[i, 1]}))^4 + Q_{22} \cdot (\sin(\theta_{[i, 1]}))^4 + 2 \cdot (Q_{12} + 2 \cdot Q_{66}) \cdot (\cos(\theta_{[i, 1]}))^2 \cdot (\sin(\theta_{[i, 1]}))^2 :$$

$$Q_{bar}[1, 2, i] := (Q_{11} + Q_{22} - 4 \cdot Q_{66}) \cdot (\sin(\theta_{[i, 1]}))^2 \cdot (\cos(\theta_{[i, 1]}))^2 + Q_{12} \cdot ((\cos(\theta_{[i, 1]}))^4 + (\sin(\theta_{[i, 1]}))^4) :$$

$$Q_{bar}[1, 3, i] := (Q_{11} - Q_{12} - 2 \cdot Q_{66}) \cdot (\sin(\theta_{[i, 1]})) \cdot (\cos(\theta_{[i, 1]}))^3 - (Q_{22} - Q_{12} - 2 \cdot Q_{66}) \cdot (\sin(\theta_{[i, 1]}))^3 \cdot \cos(\theta_{[i, 1]} :$$

$$Q_{bar}[2, 2, i] := Q_{11} \cdot (\sin(\theta_{[i, 1]}))^4 + Q_{22} \cdot (\cos(\theta_{[i, 1]}))^4 + 2 \cdot (Q_{12} + 2 \cdot Q_{66}) \cdot (\cos(\theta_{[i, 1]}))^2 \cdot (\sin(\theta_{[i, 1]}))^2 :$$

$$Q_{bar}[2, 3, i] := (Q_{11} - Q_{12} - 2 \cdot Q_{66}) \cdot (\cos(\theta_{[i, 1]})) \cdot (\sin(\theta_{[i, 1]}))^3 - (Q_{22} - Q_{12} - 2 \cdot Q_{66}) \cdot (\cos(\theta_{[i, 1]}))^3 \cdot \sin(\theta_{[i, 1]} :$$

$$Q_{bar}[3, 3, i] := (Q_{11} + Q_{22} - 2 \cdot Q_{12} - 2 \cdot Q_{66}) \cdot (\cos(\theta_{[i, 1]}))^2 \cdot (\sin(\theta_{[i, 1]}))^2 + Q_{66} \cdot ((\cos(\theta_{[i, 1]}))^4 + (\sin(\theta_{[i, 1]}))^4) :$$

$$Q_{bar}[2, 1, i] := Q_{bar}[1, 2, i] :$$

$$Q_{bar}[3, 1, i] := Q_{bar}[1, 3, i] :$$

$$Q_{bar}[3, 2, i] := Q_{bar}[2, 3, i] :$$

end do:

> # Calculate elements of extensional stiffness matrix [A], coupling stiffness matrix [B], and bending stiffness matrix [Dm]
Units: [A]--> MPa.m; [B]--> MPa.m^2; [Dm]--> MPa.m^3

> for i from 1 by 1 to 3

while true do

for j from 1 by 1 to 3

while true do

$$A[i, j] = 0 :$$

$$B[i, j] := 0 :$$

$$Dm[i, j] := 0 :$$

for k from 1 by 1 to n

while true do

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A[i,j] := A[i,j] + Qbar[i,j,k]·(h[k+1,1] - h[k,1]) :
B[i,j] := B[i,j] +  $\frac{1}{2}$ ·Qbar[i,j,k]·(h[k+1,1]2 - h[k,1]2) :
Dm[i,j] := Dm[i,j] +  $\frac{1}{3}$ ·Qbar[i,j,k]·(h[k+1,1]3 - h[k,1]3) :

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end do:
end do:
end do:

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> evalf( A );
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$$\begin{bmatrix} 1869.842182 & 43.45386666 & 0. \\ 43.45386666 & 1012.517281 & 0. \\ 0. & 0. & 107.5500000 \end{bmatrix}$$

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> evalf( B );
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$$\begin{bmatrix} 0. & 0. & 0. \\ 0. & 0. & 0. \\ 0. & 0. & 0. \end{bmatrix}$$

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> evalf( Dm );
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$$\begin{bmatrix} 0.04934828925 & 0.0008147599997 & 0. \\ 0.0008147599997 & 0.004695950685 & 0. \\ 0. & 0. & 0.002016562500 \end{bmatrix}$$

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> # Total thickness
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> h := 0.015 :
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> # Astar (in 1/(MPa.m)) and Dstar (in 1/(MPa.m^3)) matrices
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> Astar := MatrixInverse(A) :
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  Dstar := MatrixInverse(Dm) :
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> # In-plane engineering constants in GPa
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> Ex :=  $\frac{1}{Astar[1,1]·h} · \frac{1}{1000}$  ;
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  Ey :=  $\frac{1}{Astar[2,2]·h} · \frac{1}{1000}$  ;
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  Gxy :=  $\frac{1}{Astar[3,3]·h} · \frac{1}{1000}$  ;
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  nuxy := -  $\frac{Astar[1,2]}{Astar[1,1]}$  ;
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  nuyx := -  $\frac{Astar[1,2]}{Astar[2,2]}$  ;
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  Ex := 124.531819125896
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  Ey := 67.4338295034442
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  Gxy := 7.170000000000000
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  nuxy := 0.0429166666835388
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  nuyx := 0.0232393231248647
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> # Flexural engineering constants in GPa
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$$\text{> } Exf := \frac{12}{Dstar[1, 1] \cdot h^3} \cdot \frac{1}{1000};$$

$$Eyf := \frac{12}{Dstar[2, 2] \cdot h^3} \cdot \frac{1}{1000};$$

$$Gxyf := \frac{12}{Dstar[3, 3] \cdot h^3} \cdot \frac{1}{1000};$$

$$nuxyf := -\frac{Dstar[1, 2]}{Dstar[1, 1]};$$

$$nuyx := -\frac{Dstar[1, 2]}{Dstar[2, 2]};$$

$$Exf := 174.957959863389$$

$$Eyf := 16.6488841650510$$

$$Gxyf := 7.17000000000000$$

$$nuxyf := 0.173502673761575$$

$$nuyx := 0.0165104000986215$$

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