

## Euler's Method for System of ODE's

Original IVP:

$$m \frac{d^2 x}{dt^2} + c \frac{dx}{dt} + kx = 0, \quad 0 < t < 15 \text{ s},$$

$$x(0) = 1 \text{ m},$$

$$\dot{x}(0) = 0,$$

$$m = 20 \text{ kg}, c = 5 \text{ N} \cdot \text{s/m}, k = 20 \text{ N/m}.$$

System of ODE's:

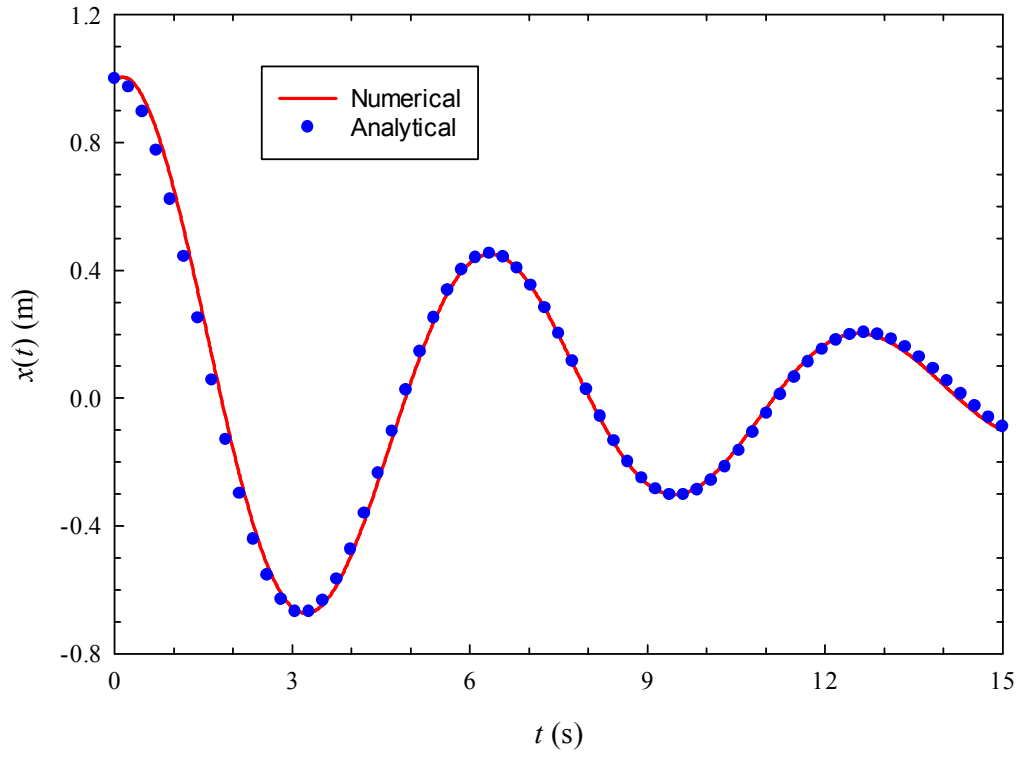
$$\frac{dx}{dt} = v = f_1,$$

$$\frac{dv}{dt} = -\frac{c}{m}v - \frac{k}{m}x = f_2,$$

$$x(0) = 1 \text{ m}, v(0) = 0.$$

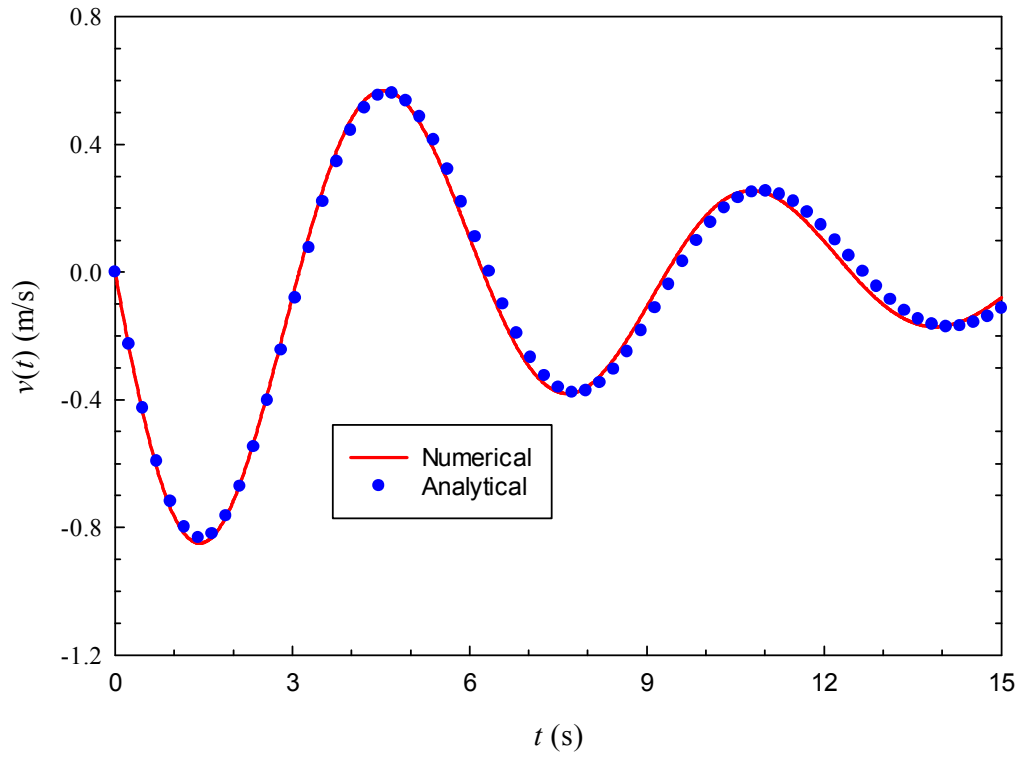
Numerical solution is developed by applying Euler's method. Accuracy can be improved by increasing the number of intervals. 128 intervals results in a better result especially for the velocity function.

$x(t)$  versus time



**Fig. 1:** Analytical and numerical solutions for position. Number of intervals = 64.

$v(t)$  versus time



**Fig. 2:** Analytical and numerical solutions for velocity. Number of intervals = 64.