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> # Prof. Dr. Serkan Dağ
# ME 310 Numerical Methods
# File 9.2
# Lagrange Interpolating Polynomials
> restart :
with(CurveFitting) :
Digits := 16 :
> # Linear Interpolation
> # Generate the 1-st order polynomial
> f1L := PolynomialInterpolation( [0.10377, 0.11144], [6.4147, 6.5453], v, form = Lagrange);
      f1L := 17.0273794002607 v + 4.64776883963495 (1)
> # Same result needs to be found by Newton form
> f1N := PolynomialInterpolation( [0.10377, 0.11144], [6.4147, 6.5453], v, form = Newton);
      f1N := 17.02737940026076 v + 4.647768839634941 (2)
> subs(v=0.108, f1L);
      6.486725814863106 (3)
> # Quadratic Interpolation
> # Generate the 2-nd order polynomial
> f2L := expand( PolynomialInterpolation( [0.10377, 0.11144, 0.1254], [6.4147, 6.5453, 6.7664], v, form
      = Lagrange) );
      f2L := -54.98245574384 v2 + 28.86015370090 v + 4.0119446396729 (4)
> # Newton form
> f2N := expand( PolynomialInterpolation( [0.10377, 0.11144, 0.1254], [6.4147, 6.5453, 6.7664], v, form
      = Newton) );
      f2N := -54.98245574383980 v2 + 28.86015370089253 v + 4.011944639672877 (5)
> subs(v=0.108, f2L);
      6.487525875573950 (6)
> # Inverse interpolation to find v for s = 6.6 kj/(kgK)
> solve(f2L = 6.6, v);
      0.1147707902952466, 0.4101267121982350 (7)
>

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