

# DIAGONALIZATION OF REAL SYMMETRIC MATRICES

(Def) A square matrix  $A$  is called **symmetric** if  $A^T = A$ .

We consider the **standard inner product**

$$(X|Y) = X^T \cdot Y \quad (X, Y \in M^{n \times 1})$$

on the space of all  $n \times 1$ -matrices.

Theorem Let  $A$  be a real symmetric matrix.

Then

a) all eigenvalues are real.

(this means that all roots of  $\Delta_A(\lambda) = 0$  are real numbers).

b) eigenvectors corresponding to distinct eigenvalues are orthogonal.

(This means that if  $P_1$  corresponds to  $\lambda_1$  and  $P_2$  corresponds to  $\lambda_2$ , and  $\lambda_1 \neq \lambda_2$ ,

then  $(P_1|P_2) = P_1^T \cdot P_2 = 0$ )

Proof (b) only)

Let  $\lambda_1 \neq \lambda_2$  be eigenvalues corresponding to  $P_1$  and  $P_2$ .

$$\begin{aligned} \text{Then } \lambda_1 (P_1|P_2) &= (\lambda_1 P_1|P_2) = (A P_1|P_2) = (A P_1)^T \cdot P_2 = \\ &= P_1^T A^T P_2 = P_1^T A P_2 = P_1^T \lambda_2 P_2 = \lambda_2 (P_1|P_2). \end{aligned}$$

Since  $\lambda_1 \neq \lambda_2$ , the equality  $\lambda_1 (P_1|P_2) = \lambda_2 (P_1|P_2)$  implies  $(P_1|P_2) = 0$ .



(Def) A square matrix  $Q$  is called orthogonal if  $Q^T Q = I$ . 2

(In other words,  $Q$  is invertible and  $Q^{-1} = Q^T$ .)

Theorem A square matrix  $Q = [Q_1 Q_2 \dots Q_n]$  is orthogonal iff its columns  $\{Q_1, Q_2, \dots, Q_n\}$  form the orthonormal basis for  $M^{n \times 1}$ .

Proof  $Q$  is orthogonal  $\Leftrightarrow$

$$\Leftrightarrow Q^T Q = \begin{bmatrix} Q_1^T \\ Q_2^T \\ \vdots \\ Q_n^T \end{bmatrix} \cdot [Q_1 Q_2 \dots Q_n] = I \quad (\Leftrightarrow)$$

$$\Leftrightarrow (Q^T Q)_{ij} = Q_i^T Q_j = \delta_{ij} \quad \text{for every } i, j \quad (\Leftrightarrow)$$

$$\Leftrightarrow (Q_i | Q_j) = \delta_{ij} = \begin{cases} 1, & \text{if } i=j \\ 0, & \text{if } i \neq j \end{cases}$$

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Theorem **If**  $A$  is a real symmetric matrix then  $A$  is **diagonalizable** and there exists an orthogonal matrix  $Q$  such that  $Q^{-1} A Q$  is diagonal.

## Comments to the theorem

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The only nontrivial part of its proof is to show that  $A$  is diagonalizable.

After this we have  $P$  s.t.  $P^{-1}AP = \mathcal{D} = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_k \end{bmatrix}$ .

Collect all columns  $\{P_1, P_2, \dots, P_{m_1}\}$  corresponding to  $\lambda_1$ .

Apply Gram-Schmidt to  $\{P_1, \dots, P_{m_1}\}$  to find an

orthonormal basis  $\{Q_1, \dots, Q_{m_1}\}$  for  $\text{span}(P_1, \dots, P_{m_1})$ .

Repeat this with each eigenvalue  $\lambda_j$ .

Then we obtain an orthonormal family

$$\underbrace{Q_1, \dots, Q_{m_1}}_{\lambda_1}, \underbrace{Q_{m_1+1}, \dots, Q_{m_2}}_{\lambda_2}, \dots, \underbrace{Q_{m_{k-1}+1}, \dots, Q_{m_k}}_{\lambda_k}$$

of eigenvectors which contains  $n$  vectors.

Therefore  $Q_1, Q_2, \dots, Q_n$  is an orthonormal basis for  $M^{n \times 1}$  and

$$Q^{-1}AQ = \mathcal{D},$$

where  $Q = [Q_1 \ Q_2 \ \dots \ Q_n]$ .

The matrix  $Q$  is orthogonal since  $\{Q_1, \dots, Q_n\}$  is an orthonormal basis.

$$\text{So } Q^T A Q = \mathcal{D}.$$

## Example

Diagonalize  $A = \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix}$

by means of an orthogonal matrix.

## Solution

$A = A^T$  is symmetric.

The characteristic polynomial of  $A$  is  $|\lambda I - A|$ .

$$\begin{aligned} 0 &= \begin{vmatrix} \lambda - 2 & 1 & 1 \\ 1 & \lambda - 2 & 1 \\ 1 & 1 & \lambda - 2 \end{vmatrix} = (\lambda - 2) \begin{vmatrix} \lambda - 2 & 1 \\ 1 & \lambda - 2 \end{vmatrix} - \begin{vmatrix} 1 & 1 \\ 1 & \lambda - 2 \end{vmatrix} + \begin{vmatrix} 1 & \lambda - 2 \\ 1 & 1 \end{vmatrix} \\ &= (\lambda - 2) ((\lambda - 2)^2 - 1) - (\lambda - 2 - 1) + (1 - (\lambda - 2)) \\ &= (\lambda - 2)(\lambda^2 - 4\lambda + 3) - 2\lambda + 6 = \lambda^3 - 4\lambda^2 + 3\lambda - 2\lambda^2 + 8\lambda - 6 - 2\lambda + 6 \\ &= \lambda^3 - 6\lambda^2 + 9\lambda = \lambda(\lambda^2 - 6\lambda + 9) = \lambda(\lambda - 3)^2 = \lambda(\lambda - 3)(\lambda - 3). \end{aligned}$$

Thus, the eigenvalues are

$$\lambda_1 = 0, \quad \lambda_2 = 3, \quad \lambda_3 = 3.$$

Remark that if all eigenvalues  $\xi_1, \xi_2, \xi_3$  of a symmetric  $3 \times 3$ -matrix are distinct, we need only to find eigenvectors  $P_1, P_2, P_3$  and normalize them to get  $\{Q_1, Q_2, Q_3\}$ , which we use to construct an orthogonal matrix  $Q = [Q_1 \ Q_2 \ Q_3]$ .

But unfortunately, in our case,  $\lambda_2 = \lambda_3$

$$\textcircled{1} \quad \lambda = \lambda_1 = 0$$

$$\lambda I - A = \begin{bmatrix} -2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{bmatrix} \xrightarrow[\frac{1}{2}R_1 + R_3]{\frac{1}{2}R_2 + R_2} \begin{bmatrix} -2 & 1 & 1 \\ 0 & -\frac{3}{2} & \frac{3}{2} \\ 0 & \frac{3}{2} & -\frac{3}{2} \end{bmatrix} \xrightarrow{R_2 + R_3}$$

$$\rightarrow \begin{bmatrix} -2 & 1 & 1 \\ 0 & -\frac{3}{2} & \frac{3}{2} \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{\frac{2}{3}R_2} \begin{bmatrix} -2 & 1 & 1 \\ 0 & -1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$(\lambda I - A)X = 0, \quad X = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

$$\begin{cases} -2x + y + z = 0 \\ -y + z = 0 \\ 0 \cdot z = 0 \end{cases}$$

Take  $z$  as a free variable.

$$-2x + z = 0$$

$$y = z$$

$$X = \begin{bmatrix} z \\ z \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} z$$

$$\Rightarrow P_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$\textcircled{2} \quad \lambda = \lambda_2 = \lambda_3 = 3$$

$$\lambda I - A = 3I - A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$X = \begin{bmatrix} u \\ t \\ s \end{bmatrix}, \quad u + t + s = 0$$

We may take any pair, for example,  $\{u, s\}$ , as free variables

$$X = \begin{bmatrix} u \\ -u-s \\ s \end{bmatrix} = u \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} + s \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$$

$$P_2 = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \quad P_3 = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$$

Remark that we may take, for example,  $\tilde{P}_2 = P_2 + P_3$  and  $\tilde{P}_3 = P_2 - P_3$ , as a basis for  $\text{span}(P_3, P_2)$  instead of  $\{P_3, P_2\}$ .

③ Now, what we will do with the family 16

$$\underbrace{P_1}_{\lambda_1}, \underbrace{P_2, P_3}_{\lambda_2} ?$$

We normalize the 1-st vector and orthonormalize  $\{P_2, P_3\}$ .

Ⓐ  $\|P_1\| = \sqrt{3}$ , thus  $Q_1 = \frac{P_1}{\|P_1\|} = \begin{bmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix}$

Ⓑ Apply Gram-Schmidt to  $\{P_2, P_3\}$ .

$$\tilde{P}_2 = P_2 = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$$

$$(P_3 | \tilde{P}_2) = 1$$

$$(\tilde{P}_2 | \tilde{P}_2) = 2$$

$$\tilde{P}_3 = P_3 - \frac{(P_3 | \tilde{P}_2)}{(\tilde{P}_2 | \tilde{P}_2)} \tilde{P}_2 = P_3 - \frac{1}{2} P_2$$

$$\tilde{P}_3 = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} - \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ 0 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ -\frac{1}{2} \\ 1 \end{bmatrix}$$

$$\|\tilde{P}_2\| = \sqrt{2} \Rightarrow Q_2 = \frac{\tilde{P}_2}{\sqrt{2}} = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \\ 0 \end{bmatrix}$$

$$\|\tilde{P}_3\| = \sqrt{\frac{1}{4} + \frac{1}{4} + 1} = \frac{\sqrt{6}}{2}$$

$$Q_3 = \frac{\tilde{P}_3}{\|\tilde{P}_3\|} = \frac{\tilde{P}_3}{(\frac{\sqrt{6}}{2})} = \frac{2}{\sqrt{6}} \begin{bmatrix} -\frac{1}{2} \\ -\frac{1}{2} \\ 1 \end{bmatrix} = \begin{bmatrix} -\frac{1}{\sqrt{6}} \\ -\frac{1}{\sqrt{6}} \\ \frac{2}{\sqrt{6}} \end{bmatrix}$$

$$Q = [Q_1 \ Q_2 \ Q_3] = \begin{bmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & 0 & \frac{2}{\sqrt{6}} \end{bmatrix}$$

Remark that the diagonalizing orthogonal matrix  $Q$  is uniquely determined iff  $A$  possesses  $n$  distinct eigenvalues!!! For example, (see p.243 of the text book)

$$Q_1 = \begin{bmatrix} \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & 0 & -\frac{2}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \end{bmatrix} \text{ is another solution of our problem.}$$

## Exercise

Diagonalize  $A = \begin{bmatrix} 4 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & -1 & 0 \end{bmatrix}$  by means of

an orthogonal matrix  $Q$ .

## Solution

$$|\lambda I - A| = \begin{vmatrix} \lambda - 4 & 0 & 0 \\ 0 & \lambda & 1 \\ 0 & 1 & \lambda \end{vmatrix} = (\lambda - 4)(\lambda^2 - 1) = (\lambda - 4)(\lambda - 1)(\lambda + 1).$$

The eigenvalues are  $\lambda_1 = 4$ ,  $\lambda_2 = 1$ ,  $\lambda_3 = -1$ .

All eigenvalues are distinct, therefore  $Q$  is unique, and we only have to normalize basis of eigenvectors  $\{P_1, P_2, P_3\}$ .

①  $\lambda = 4$ .

$$\lambda I - A = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 4 & 1 \\ 0 & 1 & 4 \end{bmatrix} \xrightarrow{(-\frac{1}{4})R_2 + R_3} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 4 & 1 \\ 0 & 0 & \frac{15}{4} \end{bmatrix}$$

$$X = \begin{bmatrix} u \\ t \\ v \end{bmatrix} \begin{cases} 4t + v = 0 \\ \frac{15}{4}v = 0 \end{cases}$$

$u = u$  - is a free variable.

$$X = \begin{bmatrix} u \\ 0 \\ 0 \end{bmatrix} = u \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \Rightarrow P_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = Q_1 \quad \text{since } \|P_1\| = 1.$$

②  $\lambda = 1$

$$\lambda I - A = \begin{bmatrix} -3 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} \xrightarrow{-R_2 + R_3} \begin{bmatrix} -3 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$X = \begin{bmatrix} u \\ t \\ v \end{bmatrix} \begin{cases} -3u = 0 \\ t + v = 0 \end{cases} \Rightarrow \begin{cases} u = 0 \\ t = -v \end{cases}$$

Choose  $t$  as a free variable

$$X_1 = \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} t \quad P_2 = \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} \quad \|P_2\| = \sqrt{2} \Rightarrow Q_2 = \begin{bmatrix} 0 \\ \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{bmatrix}$$

$$(3) \lambda = -1$$

$$\lambda I - A = \begin{bmatrix} -5 & 0 & 0 \\ 0 & -1 & 1 \\ 0 & 1 & -1 \end{bmatrix} \xrightarrow{\substack{R_2+R_3 \\ (-\frac{1}{5}) \cdot R_1}} \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$X = \begin{bmatrix} u \\ t \\ v \end{bmatrix} \quad \begin{cases} u = 0 \\ -t + v = 0 \end{cases}$$

Choose  $t$  as a free variable

$$X = \begin{bmatrix} 0 \\ t \\ t \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} t$$

$$P_3 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

$$\|P_3\| = \sqrt{2} \Rightarrow$$

$$Q_3 = \begin{bmatrix} 0 \\ \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

$$Q = [Q_1 \ Q_2 \ Q_3] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 0 & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}$$